

1954

# Normal frequencies of vibration of 1, 3-Butadiene

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BOSTON UNIVERSITY  
GRADUATE SCHOOL

Dissertation  
THE NORMAL FREQUENCIES OF VIBRATION  
OF 1, 3- BUTADIENE

by

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(A.B., Boston University, 1949; A.M. Boston University, 1949)

Submitted in partial fulfilment of the  
requirements for the degree of  
Doctor of Philosophy  
1954



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## TABLE OF CONTENTS

	Page
A. Introduction . . . . .	i
B. THEORY OF MOLECULAR VIBRATIONAL SPECTRA . . . . .	1
1. Molecular Structure . . . . .	1
2. Interatomic Forces . . . . .	1
3. The Rotation of Molecules . . . . .	4
4. Vibration of Molecules . . . . .	5
5. Potential Functions . . . . .	6
6. Mathematical Methods . . . . .	8
a. Classical . . . . .	8
b. Quantum mechanical . . . . .	13
C. THE NORMAL VIBRATIONS OF 1, 3- BUTADIENE . . . . .	18
1. The Configuration of 1, 3, Butadiene . . . . .	18
2. The Potential Function . . . . .	22
3. Calculation of the Vibrational Frequencies . . . . .	25
a. An Exact Method for Expanding the Secular Equation . . . . .	27
b. The Determination of the Normal Frequencies . . . . .	36
4. Comparison of Results with Observed Spectra . . . . .	37
5. An Approximate Calculation . . . . .	41
6. Calculation of Heat Capacity . . . . .	45
7. Evaluation of Results . . . . .	48
Bibliography . . . . .	50
Abstract . . . . .	52
Autobiography . . . . .	58
Figure 1 . . . . .	20
Figure 2 . . . . .	39a
Figure 3 . . . . .	40
Table 1 . . . . .	21
Table 2 . . . . .	26
Table 3 . . . . .	38
Table 4 . . . . .	44



## A. INTRODUCTION

Within the past several decades, interest in the study of infra-red and Raman spectra has grown considerably. When Rawlins and Taylor published their book<sup>1</sup> on infra-red analysis in 1928, there wasn't a single book available concerned with infra-red study of molecular structure. Since then a number of books have appeared, and many articles have been published on the subject.

There are several reasons for the growth of interest. One of the important reasons is the application of infra-red study to chemical analysis. It is possible by an analysis of the infra-red spectrum of a substance not only to identify elements but atomic and molecular groups as well. For example, an ethyl or a methyl group in a compound will always exhibit certain characteristic frequencies.

Secondly, the study of molecular spectra has probably become the most important means for investigating molecular structure. Various energy levels may be obtained from a study of the spectra which, in turn, give detailed information on the electronic motion, vibration, and rotation of the atoms in the molecules. A theoretical understanding of valence has resulted from a study of electronic motion while the forces acting between atoms in a molecule may be obtained from the vibrational frequencies and accurate infor-

1. Rawlins, F. I. G., and Taylor, A.M., Infra-Red Analysis of Molecular Structure (Cambridge University Press, 1929)



mation concerning the geometrical arrangement of the atoms may be obtained from a study of the rotational spectra.

Furthermore, the Raman effect was discovered in 1928 which also has become important in the field of analysis and theoretical studies. It is sometimes possible to obtain information about a molecule from the Raman spectrum which cannot be obtained by other means.

The theoretical aspects of the study of molecular structure made considerable strides forward when group theory was introduced. The determination of the structure of polyatomic molecules and the forces acting between the atoms is an extremely complex problem but a great deal of simplification is introduced by the application of group theory to the symmetry of the molecule.

The advance of theoretical methods always requires an improvement of experimental techniques. The improved experimental methods then uncover further information for use in theoretical study. As a consequence of improved methods in both endeavors, much work is being done at the present time in molecular studies. It is with the theoretical aspects of the problem that this paper is concerned.

The infra-red spectrum is divided into three general regions called the photoelectric, near infra-red and far infra-red<sup>2</sup>. The photoelectric region extends from

2. Harrison, George R., Lord, Richard C., and Loofbourow, John R., Practical Spectroscopy (New York: Prentice-Hall, Inc., 1948)



about 0.75 microns to about 2 microns while the near infra-red extends from about 2 microns to about 25 microns and the far infra-red from about 25 microns to about 1 mm. It is divided into these regions because of the experimental techniques involved. In the photoelectric portion, ordinary prisms, gratings and photographic technique are utilized. However, in the near and far infra-red, the detection of the spectra is primarily accomplished by utilizing the heating effect of the radiant energy. In the near infra-red prisms are still used, but they are made of rock salt or potassium bromide, while in the far infra-red, gratings are used primarily.

These divisions in a general way agree with the division of the molecular energy levels into electronic, vibrational and rotational regions. Infra-red in general corresponds to oscillations of particles which are several hundred times slower than the motion of electrons. This motion is attained by the atoms in a molecule.

The Raman effect is a scattering process which differs from the Tyndall effect in that with the Raman effect there is a change of frequency associated with the scattering. The incident quanta collide with a vibrating atom and are scattered with either a higher or lower energy, depending on the nature of the collision, and hence will have a resultant higher or lower frequency. The change in frequency is characteristic of the frequency of vibration



of the atom with which the quantum of light collides. The Raman lines will then appear in a position displaced from the incident spectral line by an amount which is characteristic for the medium through which the light has been scattered. The lines which are displaced to the longer wave length side are called Stokes lines and those displaced to shorter wave lengths are called anti-Stokes after a similar phenomenon which appears in fluorescence and was discovered by Stokes. In fluorescence, however, there is an actual absorption of the light quanta which after a short time are reemitted with a change of wave length. Since a relatively small amount of the light quanta will collide with atoms, the intensity of the Raman lines will be rather low and hence the experimental difficulties in observing the lines are correspondingly greater.

The vibration of the atoms in a molecule give rise to the major portion of the near infra-red and to Raman lines. A knowledge of the vibration of the atoms will yield information concerning the structure of the molecule and particularly the forces acting between the atoms in a molecule. These can then be used to calculate the energy of dissociation and other thermodynamic quantities for the molecule, such as, heat capacities, etc. It is with this facet of the problem, that is, a determination of the normal frequencies of vibration of 1, 3- butadiene, that we concern ourselves primarily in this paper.



## B. THEORY OF MOLECULAR VIBRATIONAL SPECTRA

### 1. Molecular Structure

The atoms in a molecule are continually in motion vibrating about an equilibrium position and rotating about their center of mass as long as the molecule possesses any thermal energy. The equilibrium configuration is best determined from a study of the rotational spectra or electron diffraction patterns. The vibrations of the atoms are then considered in terms of the displacements from these equilibrium configurations.

A knowledge of the number and size of the atoms and their configuration permits a utilization of their symmetry properties in the determination of the frequencies of vibration. The particular configuration which the atoms will be in is determined by the forces which are acting between them. These forces also determine the normal frequencies of vibration.

### 2. Interatomic Forces

There are essentially two types of forces acting between the atoms in a molecule<sup>3</sup>. First, there are the forces of attraction which are often called the valence forces and which fall off rapidly as the distance between the atoms becomes larger. Secondly, there are forces of repulsion which are negligible at large distances but which

3. Slater, J. C., Introduction to Chemical Physics (New York: McGraw-Hill, 1939) p. 130



increase even more rapidly than the attraction at small distances. At the point where the attraction and repulsion forces just balance is the equilibrium position. This is the normal distance of separation for any two atoms, and any small displacement from this position will give rise to forces tending to restore the atoms to the equilibrium position. This point is then also a minimum potential energy position, and the amount of work required to pull the two atoms apart is the energy of dissociation.

When two atoms approach each other, there is first of all a small force between them which is the Van der Waal's attraction<sup>4</sup>. This force arises from the polarization of each atom by the fluctuating dipole of the other and the overall effect is rather small. As the atoms approach still closer, the electronic charge of one is attracted by the nuclear charge of the other. This is essentially a coulomb attraction even though each atom is electrically neutral. This results when the electronic charge distribution of one overlaps the electronic charge distribution of the other. As the overlapping increases and the nucleus of one begins to penetrate the electronic charge distribution of the other, strong repulsion sets up between the two nuclei.

A still more important factor must be considered, and that is the fact that when atoms begin to overlap, a

4. Ibid, p. 368



distortion of charge distribution takes place. When two atoms overlap, some of the charge shifts from the region between the atoms to the far sides of the nuclei. This results in an increase of energy and hence a repulsion between the atoms. However, this overlapping and distortion also results in a force of attraction which is greater than the previous forces of attraction. This is the exchange effect which refers to an exchange of electrons between the two atoms. This results in a piling up of electrons between the two atoms and a lowering of the potential energy, and hence a binding effect is produced. The electrons involved in this interaction are the outer or valence electrons and the type of attraction is called homopolar valence attraction. It is necessary, however, from the exclusion principle that the electrons entering into the exchange effect have opposite spins.

When more than two atoms are involved, the number of atoms which can enter into the attractive exchange type of interaction is determined by the number of valence electrons. Only two electrons can enter into an electron-pair bond and if there is only one valence electron on the atom involved, then there will be repulsion to any other atom that may approach. If an atom has a number of valence electrons, however, then it can form a bond with a number of other atoms depending on the number of valence electrons.



### 3. The Rotation of Molecules

To a fairly good approximation, the rotation and vibration of the atoms can be treated separately considering the vibrations as if the molecules were not rotating and the rotation as if there were no vibration<sup>5</sup>. This assumes that the amplitude of vibration is small as compared to the internuclear distances and that the forces between atoms that are induced by rotation are small as compared to the forces between atoms which give rise to the restoring forces resulting in vibrations.

The far infra-red bands correspond to a change of rotational quantum number alone and they will have an intensity only if the molecule possesses a permanent dipole moment since otherwise the average value of the dipole moment will be zero and no dipole radiation will occur. Any molecules which possess electrical symmetry will have no permanent dipole moment, and hence the only rotational spectra which can be observed in these cases are those that arise due to the formation of a dipole moment because of unsymmetrical vibration of the atoms. These are generally observed as fine structure on the vibrational band spectra. We are here concerned primarily with the vibrational spectra of molecules.

5. Dennison, David M., Rev. Mod. Phy. 3, 280 (1931)



#### 4. Vibration of Molecules

When the atoms in a molecule are in their equilibrium position, there are forces acting on them, as previously discussed, which will tend to return them to this position if they are displaced. This point is a potential energy minimum and any displacement tends to increase the potential energy. If the force function tending to restore the atoms to the equilibrium position is linear in this neighborhood, then for small displacements the atoms will perform simple harmonic oscillations about this position. Dennison has shown that under these conditions the frequency of radiation absorbed or emitted is very nearly that of the classical frequency of mechanical vibrations. Since infra-red absorption bands are concerned with transitions from the lowest energy states to those immediately above it, it is possible to consider only vibrations of the lowest energy states where the force function is nearly linear and hence classical methods may be used for the determination of the vibrational frequencies. However, to determine intensities and selection rules quantum mechanics must be used.

In general, the normal modes of vibration of a molecule are determined as a function of the mutual displacements of the particles from their equilibrium positions. While normal vibrations may be determined by considering the forces acting on the particle, in practice usually the conservation of energy principle is utilized. This requires setting up the kinetic and potential energy in terms of the



displacement coordinates. The type of potential function that is used is determined to a certain extent by the type of molecule which is being considered.

### 5. Potential Functions

Usually the potential function is developed as a power series in the displacement coordinates in which case all linear terms are absent since they refer to the rest position: the quadratic terms give the normal vibrations, and higher order terms give an harmonic corrections. Several different choices of the coordinates are possible and the potential function will, to a certain extent, depend on the choice of these internal coordinates.

If the center of mass and angular momentum of the molecule are not considered fixed, there will be  $3N$  coordinates where  $N$  is the number of atoms in the molecule. However, since there is no restoring force for simple translation or for rotation about any axis, these motions give non-genuine normal vibrations. Thus, if we fix the center of mass and set the angular momentum equal to zero, the number of coordinates will be reduced by five if it is a linear molecule or by six if it is non-linear. This will leave either  $3N-5$  or  $3N-6$  internal coordinates. One choice of coordinates will then be to use  $3N-6$  internuclear distances and deviations from these  $3N-6$  internuclear distances as internal coordinates. Such coordinates are sometimes called central force coordinates since they work particularly



well with a central force system<sup>6</sup>. In this type of force field, the assumption is made that the force acting on any one atom is the resultant of the attractions and repulsions of all the other atoms in the molecule and depends only on the distance between atoms and acts along the line connecting the atoms. This type of force field has been found to work fairly well for molecules composed of heavy atoms.

The type of internal coordinates that seem to work best in actual practice are symmetry coordinates<sup>7,8,9</sup>. These are based on the symmetry properties of the molecules. For a given value of one of these coordinates there correspond displacements of the nuclei in agreement with one of the symmetry types. These symmetry types will be discussed later in the discussion on symmetry and group theory.

In the establishment of the potential energy expression, there are usually more potential constants than normal frequencies. Hence only in a few cases is it possible to obtain the values of the potential constants on a purely theoretical basis. One way to solve this difficulty is to consider an isotope effect<sup>10</sup> where one or several atoms are

6. Shaffer, W. H. and Newton, R.R., J. Chem. Phy., 10, 405 (1942)
7. Howard, J. B. and Wilson, E. B. Jr., J. Chem. Phy. 2, 620 (1934)
8. Redlich, O. and Tompa, H., J. Chem. Phy. 5, 529 (1937)
9. Rosenthal, J. E. and Murphy, G. M., Rev. Mod. Phy. 8, 317 (1936)
10. Herzberg, Gerhardt, Molecular Spectra and Molecular Structure., II. Infra-red and Raman Spectra of Polyatomic Molecules (New York: D. Van Nostrand Co., Inc., 1945) p. 227 ff.



replaced by isotopic atoms for which the force constants are the same but the frequencies are different. This gives additional equations in the same constants and permits solving for them. Another solution is to make special assumptions about the forces acting in the molecules thus reducing the number of constants. One such assumption is the central force field assumption which has already been mentioned.

Another type of force field assumption is the valence force<sup>11</sup>. This assumes that there is a strong restoring force along the line of every valence bond and another opposing the change of the angle between two valence bonds. This type of force field appears to be a better approximation in most cases than the central force field.

Another type of more general force field could be mentioned and that is the Urey-Bradley field<sup>12</sup>. This type of field seems to apply fairly well to molecules containing heavy atoms in a tetrahedral form. A repulsive interaction is assumed between the corner atoms of the molecule thus adding terms of the order  $1/r_j^n$  to the potential energy expression.

## 6. Mathematical Methods

(a) Classical - Since, as has been indicated, the vibrations of the atoms in the molecule for small displacements can be considered on the basis of classical

11. Wilson, E. B., Jr., J. Chem. Phy. 9, 76 (1941)

12. Urey, H. C. and Bradley, C. A., Phy. Rev. 38, 1969 (1931)



vibrations, it is possible to use classical methods to determine the normal frequencies of vibration. The mathematical methods outlined here follow in major part the development as given by Herzberg<sup>13</sup>. In practice, the energy principle is generally utilized in developing normal vibrations so that is the method that will be outlined here.

Consider a molecule which has  $N$  atoms. If a particle is displaced from rest, there will be a restoring force which will depend only on the components of the displacement from the rest position  $x_1, y_1, z_1$ . The particle oscillating in simple harmonic motion about its rest position will have a kinetic energy

$$T_1 = 1/2 m_1 v_1^2 = 1/2 m_1 \dot{s}_1^2 \quad (1)$$

and potential energy

$$V_1 = 2\pi^2 \nu_1^2 m_1 s_1^2 = 1/2 k_1 s_1^2 \quad (2)$$

where

$$k_1 = 4\pi^2 \nu_1^2 m_1. \quad (3)$$

If we let  $x_1, y_1, z_1, x_2, y_2, z_2, \dots$  be represented by  $q_1, q_2, q_3, q_4, q_5, q_6, \dots$ , we can write

$$V = 1/2 \sum_{ij} k_{ij} q_i q_j = 1/2 k_{11} q_1^2 + 1/2 k_{22} q_2^2 + k_{12} q_1 q_2 + \dots \quad (4)$$

where the force constants  $k_{ij} = k_{ji}$

The kinetic energy is then given by

$$T = \sum_i 1/2 m_i (\dot{x}_i^2 + \dot{y}_i^2 + \dot{z}_i^2) \quad (5)$$

13. Herzberg, Op. Cit., p. 72 ff.



$$\text{or } T = 1/2 \sum_{ij} a_{ij} \dot{q}_i \dot{q}_j \quad (6)$$

$$\text{where } a_{ij} = 0 \text{ for } i \neq j, \text{ and } a_{11} = a_{22} = a_{33} = m_1, \\ a_{44} = a_{55} = a_{66} = m_2 \dots \quad (7)$$

We can now transform to new coordinates  $\eta_1, \eta_2 \dots \eta_{3N}$  by a linear transformation

$$\begin{aligned} q_1 &= c_{11} \eta_1 + c_{12} \eta_2 + c_{13} \eta_3 + \dots \\ q_2 &= c_{21} \eta_1 + c_{22} \eta_2 + c_{23} \eta_3 + \dots \\ q_3 &= c_{31} \eta_1 + c_{32} \eta_2 + c_{33} \eta_3 + \dots \\ &\vdots \\ q_{3N} &= c_{3N1} \eta_1 + c_{3N2} \eta_2 + c_{3N3} \eta_3 + \dots \end{aligned} \quad (8)$$

By appropriate choice of the coefficients  $c_{ik}$  both  $V$  and  $T$  can be brought to a simpler form in terms of the new coordinates.

$$V = 1/2 (\lambda_1 \eta_1^2 + \lambda_2 \eta_2^2 + \dots + \lambda_i \eta_i^2 + \dots + \lambda_{3N} \eta_{3N}^2) \quad (9)$$

$$T = 1/2 (\dot{\eta}_1^2 + \dot{\eta}_2^2 + \dots + \dot{\eta}_i^2 + \dots + \dot{\eta}_{3N}^2) \quad (10)$$

The  $\lambda_i$  are roots of the secular equation<sup>14</sup>

$$\begin{vmatrix} k_{11} - a_{11}\lambda & k_{12} - a_{12}\lambda & k_{13} - a_{13}\lambda & \dots \\ k_{21} - a_{21}\lambda & k_{22} - a_{22}\lambda & k_{23} - a_{23}\lambda & \dots \\ \vdots & \vdots & \vdots & \ddots \end{vmatrix} = 0 \quad (11)$$

The total energy is now

$$H = T + V = 1/2(\dot{\eta}_1^2 + \lambda_1 \eta_1^2) + 1/2(\dot{\eta}_2^2 + \lambda_2 \eta_2^2) + \dots \quad (12)$$

It is thus the sum of  $3N$  mutually independent terms each of which has the form of a simple harmonic oscillator. The

14. Whittaker, E. T., Analytical Dynamics, 4th Ed. (New York, Dover Publications, 1944) p. 181



motion of the entire system is then equivalent to the superposition of  $3N$  simple harmonic motions in the normal coordinates. Thus:

$$\eta_i = \eta_i^0 \cos(2\pi\nu_i t + \phi_i) \quad (13)$$

where now

$$\lambda_i = 4\pi^2\nu_i^2 \quad (14)$$

We have that

$$k_{11} = k_{xx}^{11}, \quad k_{22} = k_{yy}^{11}, \quad \dots \quad k_{12} = k_{xy}^{11}, \quad \dots \quad (15)$$

Substituting these values and those from Eq. (7) in Eq. (11) gives

$$\begin{vmatrix} k_{xx}^{11} - m_1\lambda & k_{xy}^{11} & k_{xz}^{11} & k_{xx}^{12} & \dots & k_{xz}^{1N} \\ k_{yx}^{11} & k_{yy}^{11} - m_1\lambda & k_{yz}^{11} & k_{yx}^{12} & \dots & k_{yz}^{1N} \\ k_{zx}^{11} & k_{zy}^{11} & k_{zz}^{11} - m_1\lambda & k_{zx}^{12} & \dots & k_{zz}^{1N} \\ k_{xx}^{21} & k_{xy}^{21} & k_{xz}^{21} & k_{xx}^{22} - m_2\lambda & \dots & k_{xz}^{2N} \end{vmatrix} = 0 \quad (16)$$

The form of any normal vibration is obtained by putting all other  $\eta$ 's in Eq. (8) equal to zero. Then for  $\eta_j$

$$\begin{aligned} x_1^{(j)} &= c_{1j}\eta_j, & y_1^{(j)} &= c_{2j}\eta_j, & z_1^{(j)} &= c_{3j}\eta_j \\ x_2^{(j)} &= c_{4j}\eta_j, & y_2^{(j)} &= c_{5j}\eta_j, & z_2^{(j)} &= c_{6j}\eta_j \end{aligned} \quad (17)$$

As previously discussed, either five or six of these roots are non-genuine and correspond to translation and rotation, hence there are actually only  $3N-5$  or  $3N-6$  normal vibrations. This still gives a large secular equation to solve even if  $N$



is only moderately large. A considerable amount of simplification can be realized if the molecule possesses any symmetry. The application of group theory to polyatomic molecules is discussed in detail by Rosenthal and Murphy<sup>15</sup> and others<sup>16,17</sup>.

It is shown in the references cited that if a symmetry operation is carried out which transforms the molecule into a form indistinguishable from its original form, then the force field and potential energy will also be the same as before and, of course, the normal vibrations will be the same. However, this need not necessarily be the case for the displacements in a vibrating molecule. The  $N$  normal frequencies may then be divided into a number of symmetry classes each of which will contain a given number of frequencies. These classes or irreducible representations, as they are called in group theory, will all be along the principal diagonal of the secular equation and can be treated as separate equations. These symmetry operations aid in assigning the normal modes of vibration to certain displacements of the atoms.

The actual determination of the frequencies of vibration now requires the complete solution of the secular equation which can usually only be done for very simple cases if the force constants are not known. In order to reduce the

15. Rosenthal, J.E. and Murphy, Rev. Mod. Phy., 8, 317 (1936)
16. Meister, A.G., Cleveland, F.F. and Murray, M.J., Am. J. Phy. 11, 239 (1943)
17. Herzberg, Op. Cit., P. 1 ff. and p. 82 ff.



number of force constants, it is necessary to introduce a force field assumption. The various types of assumptions that have been made and the manner in which the calculations are then carried out are given in detail in Herzberg<sup>18</sup>.

When the molecule is rather large, the calculations become complex and it is almost impossible to carry out algebraic calculations and obtain expressions relating the force constants to the frequencies. The computations are then best carried out numerically. An important factor that is of great aid in these cases is the fact that both bond stretching and bending force constants are invariant from one molecule to another if the bonds are in similar surroundings<sup>19,20</sup>. Also for a general check on results characteristic groups of atoms have vibrational frequencies that are essentially the same in different molecules if their frequencies differ sufficiently from the vibrational frequencies of the rest of the molecule<sup>21</sup>. The calculated values of the frequencies can then be used as an aid in assigning the observed bands to various atomic vibrations.

(b) Quantum Mechanical - While the calculation of the normal frequencies can generally be carried out entirely by classical methods, the frequencies can be determined by

18. Herzberg, Op. Cit., pp. 159-191.
19. Crawford, B.L., Jr., J. Chem. Phy. 7, 555 (1939)
20. Crawford, B.L., Jr., and Brinkley, S.R., Jr., J. Chem. Phy. 9, 69 (1941)
21. Wilson, E.B.Jr., and Wells, A.J., J. Chem. Phy. 9, 314 (1941)



quantum mechanical methods and the selection rules are determined by quantum treatment. In a wave mechanical treatment, the vibrational motion of the molecule as in the classical method may be considered as a superposition of  $3N$  simple harmonic motions to a good approximation. The Schrodinger equation in normal coordinates is<sup>22</sup>

$$\frac{1}{\Psi_i} \frac{d^2 \Psi_i}{d\xi_i^2} + \frac{8\pi^2}{h^2} (E_i - \frac{1}{2} \lambda_i \xi_i^2) = 0 \quad (1)$$

where

$$E = E_1 + E_2 + \dots + E_{3n}. \quad (2)$$

The eigenfunctions of Eq. (1) are the eigenfunctions of the ordinary simple harmonic oscillator

$$\Psi_i(\xi_i) = N_{v_i} e^{-\left(\frac{\alpha_i}{2}\right)\xi_i^2} H_{v_i}(\sqrt{\alpha_i} \xi_i) \quad (3)$$

where  $N_{v_i}$  is a normalization constant,  $\alpha_i = \frac{2\pi\nu_i}{h}$  and  $H_{v_i}(\sqrt{\alpha_i} \xi_i)$  is a Hermite polynomial of the  $v_i$ th degree. The total vibrational eigenfunction is then the product of the  $3N-5$  or  $3N-6$  harmonic oscillator eigenfunctions.

The eigenvalues of the  $i$ th harmonic oscillator are given by

$$E_i = h\nu_i (v_i + 1/2), \quad v_i = 0, 1, 2, \dots \quad (4)$$

where

$$\nu_i = 1/2\pi \sqrt{\lambda_i} \quad (5)$$

is the classical frequency of vibration of the  $i$ th normal

22. See Herzberg, Op. Cit.; Pauling, L., and Wilson, E.B. Jr., Introduction to Quantum Mechanics (New York: McGraw-Hill, 1935) or Eyring, Henry, Walter, John, and Kimball, George E., Quantum Chemistry (New York: John Wiley and Sons, 1944)



vibration. The total vibrational energy of the system can then have the values

$$E(v_1, v_2, v_3 \dots) = h\nu_1(v_1 + 1/2) + h\nu_2(v_2 + 1/2) + \dots \quad (6)$$

The eigenfunctions are either even or odd functions of the normal coordinates depending on whether the energy quantum number is even or odd. Thus if a normal vibration is antisymmetric with respect to a symmetry element,  $\Psi_i(\xi_i)$  changes sign for odd  $v_i$  but remains unchanged for even  $v_i$  if the particular symmetry operation is carried out. Since the total vibrational eigenfunction is a product of the harmonic oscillator eigenfunctions, for only non-degenerate vibrations the total eigenfunction will be symmetric with respect to a given symmetry operation if the total number of components of the  $\Psi_i(\xi_i)$  that are antisymmetric is even; and of course, it will be odd if the total number of antisymmetric components is odd. When there are degenerate vibrations, each of the degenerate eigenfunctions goes into a linear combination of the eigenfunctions belonging to the same energy level.

There are only certain combinations of symmetry properties of the normal vibrations and vibrational eigenfunctions possible because only certain combinations of symmetry elements occur in each point group and some of these are necessary consequences of others. These combinations are the symmetry types or species and are the irreducible representations of group theory. For example, if a point



group has two necessary elements of symmetry there are four possible symmetry types ++, --, +-, -+. These species along with the character tables have been worked out for all of the different point groups<sup>23</sup>.

Now, since the vibrations of the atoms have been considered as a superposition of simple harmonic oscillators, the selection rule to a good approximation is given by

$$\Delta v_1 = \pm 1 \quad (7)$$

for each normal vibration  $v_1$ . However, the presence of a fundamental in either the infra-red or Raman spectra depends on the change of the dipole moment or polarizability.

The dipole moment of a molecule is represented by the matrix<sup>24</sup>

$$\int \Psi_n \Psi_m^* M d\tau \quad (8)$$

where  $\underline{M}$  is a vector with components

$$M_x = \sum e_i x_i, \quad M_y = \sum e_i y_i, \quad M_z = \sum e_i z_i \quad (9)$$

where  $e_i$  is the charge on the ith particle with coordinates  $x_i, y_i, z_i$ , and  $\Psi_n$  and  $\Psi_m$  are the time dependent eigenfunctions in the states  $\underline{n}$  and  $\underline{m}$ , then

$$\Psi_n = \psi_n e^{2\pi i(\frac{E_n}{h})t}, \quad \Psi_m = \psi_m e^{2\pi i(\frac{E_m}{h})t} \quad (10)$$

The diagonal elements represent the permanent dipole moments in the states  $\underline{n}$ ; the off-diagonal elements correspond to a transition from the state  $\underline{n}$  to  $\underline{m}$ . The transition probability is proportional to the square of the time dependent component of Eq. (8). The vibrational selection rule is

23. See Herzberg, Op. Cit., Rosenthal + Murphy, Op. Cit., Kohlrausch, K. W. F., Der Smekal-Raman-Effekt (Berlin: J. Springer, 1931), etc.

24. Herzberg, Op. Cit., p. 251



then given by the condition that at least one of the quantities

$$\Psi_{v'} \cdot \Psi_{v''}^* M_x, \Psi_{v'} \cdot \Psi_{v''}^* M_y, \Psi_{v'} \cdot \Psi_{v''}^* M_z \quad (11)$$

is totally symmetrical. The rule may also be stated as: a vibrational transition  $v' \leftrightarrow v''$  is allowed only when there is at least one component of the dipole moment  $\underline{M}$  that has the same species as the product  $\Psi_{v'} \Psi_{v''}^*$ .

For the Raman effect the intensity depends on the induced dipole  $\vec{P}$  which is represented by

$$\int \Psi_n P^* \Psi_m d\tau \quad (12)$$

where

$$P_x = \alpha_{xx} E_x + \alpha_{xy} E_y + \alpha_{xz} E_z \quad (13)$$

$$P_y = \alpha_{yx} E_x + \alpha_{yy} E_y + \alpha_{yz} E_z \quad (14)$$

$$P_z = \alpha_{zx} E_x + \alpha_{zy} E_y + \alpha_{zz} E_z \quad (15)$$

where the  $\alpha$ 's are the components of the polarizability and  $\vec{E}$  is the electric vector. The time independent part of Eq. (12) is

$$[P^0]^{nm} = \int \Psi_n P^{0*} \Psi_m d\tau \quad (16)$$

where  $P^0$  is the amplitude of  $\vec{P}$ . The intensity of a Raman transition is proportional to the square of  $[P^0]^{nm}$ .

If the values for  $\vec{P}$  are substituted in this equation, we get the components

$$[P_x^0]^{nm} = E_x^0 \int \alpha_{xx} \Psi_n \Psi_m^* d\tau + E_y^0 \int \alpha_{xy} \Psi_n \Psi_m^* d\tau + E_z^0 \int \alpha_{xz} \Psi_n \Psi_m^* d\tau \quad (17)$$

$$[P_y^0]^{nm} = E_x^0 \int \alpha_{yx} \Psi_n \Psi_m^* d\tau + E_y^0 \int \alpha_{yy} \Psi_n \Psi_m^* d\tau + E_z^0 \int \alpha_{yz} \Psi_n \Psi_m^* d\tau \quad (18)$$

$$[P_z^0]^{nm} = E_x^0 \int \alpha_{zx} \Psi_n \Psi_m^* d\tau + E_y^0 \int \alpha_{zy} \Psi_n \Psi_m^* d\tau + E_z^0 \int \alpha_{zz} \Psi_n \Psi_m^* d\tau \quad (19)$$



Here  $E^0_x$ ,  $E^0_y$ ,  $E^0_z$  are the components of the amplitude of the light wave and the integrals are the matrix elements of the six components of the polarizability tensor. The diagonal elements correspond to Rayleigh scattering while the off diagonal elements correspond to Raman scattering. The Raman selection rule is then given by the fact that at least one of the six integrals of polarizability must be different for a Raman transition to occur or again a Raman transition is allowed if at least one of the six products

$$\alpha_{xx} \psi_r' \psi_r^{*''}, \alpha_{xy} \psi_r' \psi_r^{*''}, \dots$$

is totally symmetrical.

### C. THE NORMAL VIBRATIONS OF 1, 3-Butadiene

#### 1. The Configuration of 1, 3, Butadiene

The normal configuration for butadiene could conceivably be either in the trans- or cis- form and no final conclusion has yet been reached as to which form is the lowest energy state. Mulliken has shown<sup>25</sup> that it is possible to have isomerism about a single bond as might be the case with butadiene and his calculations with molecular orbitals seem to indicate that the trans-form is the lowest energy form. The work of Carr, Pickett and Stucklen<sup>26</sup> in the ultra-violet absorption spectrum of butadiene seems to indicate that the trans-form predominates at room temperature at least.

Rasmussen, Tunnicliff and Brattain<sup>27</sup> have obtained

25. Mulliken, R.S., Rev. Mod. Phy. 14, 269 (1942)

26. Carr, E.P., Pickett, L.W., and Stucklen, H., Rev. Mod. Phy. 14, 260 (1942)

27. Rasmussen, R.S., Tunnicliff, D.D., and Brattain, R.R., J. Chem. Phy. 11, 432 (1943)



the infra-red spectrum of butadiene and compared it with the Raman spectrum taken with the butadiene in the liquid state at the temperature of dry ice by Bradacs and Kahovec<sup>28</sup>. They found a coincidence between six frequencies in the Raman and infra-red. This seems to indicate that, since no coincidences should occur if the butadiene was in the trans-form due to its center of symmetry, the cis-form is predominant at the temperature of dry ice. Thus it would appear that the cis-form is the lower energy form but at room temperature the trans-form predominates.

The cis-form (Fig. 1) has been selected as the configuration for the present work. The work of Mulliken<sup>29</sup> and Bradac and Kahovec<sup>28</sup> indicates that all the atoms are in a plane and that all bond angles both H-C-H and C-C-H are very nearly 120°. The carbon-hydrogen bond distances are fairly well known from electron diffraction studies<sup>30</sup> and were taken to be 1.09 angstroms. The carbon-carbon single bond and carbon-carbon double bond distances were taken from the work of Mulliken who based his conclusions on the calculations of Lennard-Jones<sup>31</sup> and Penney<sup>32</sup>. The C-C distance was chosen as 1.44A. and the C=C distance as 1.35A.

28. Bradacs, K., and Kahovec, L., Zeits. fr. Physik, Chemie B48, 63 (1941)
29. Mulliken, R. S., J. Chem. Phy., 7, 121 (1939)
30. Pauling, L., Nature of the Chemical Bond (Cornell University Press, 1939)
31. Lennard-Jones, J. E., Proc. Roy. Soc. 158A, 293 (1937)
32. Penney, W. G., Proc. Roy. Soc. 158A, 318 (1937)



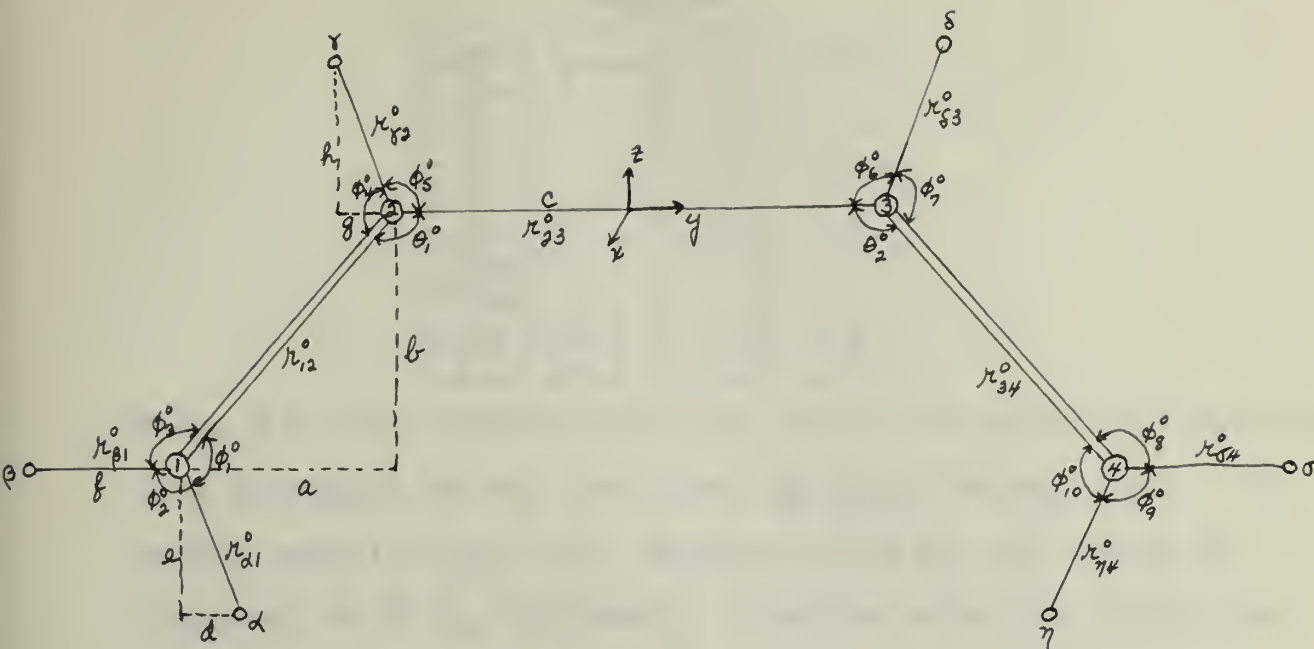


Fig. 1

The following notation has been adopted in the work that follows. The carbon atoms have been labelled with numbers from 1 to 4 while the hydrogen atoms have been lettered with Greek letters as shown in Fig. 1. The masses of the carbon atoms have been denoted by  $\underline{M}$  and the hydrogen atoms by  $\underline{m}$ . The C-C-C angles have been denoted by  $\underline{\theta}$  and the C-C-H and H-C-H angles by  $\underline{\phi}$ . The principle axis of symmetry is chosen as the  $\underline{z}$  axis.

With the configuration that was decided upon the point group for the molecule is  $C_{2v}$  with the character table as given in Table 1<sup>33</sup>.

33. See Rosenthal and Murphy, Rev. Mod. Phys., 8, 317 (1936)



Table 1

$C_{2v}$	$E$	$C_2$	$\sigma_v$	$\sigma_v'$
$A_1$	1	1	1	1
$B_2$	1	-1	-1	1
$A_2$	1	1	-1	-1
$B_1$	1	-1	1	-1
$\Phi_R$	0	$\pi$	0	0
$U_R$	10	0	10	0
$\pm 1 + \cos \phi_R$	3	-1	1	1
$\chi_R$	30	0	10	0
$\Xi$	24	2	10	0

where  $\phi$  is the angle of rotation,  $U_R$  is the number of particles left unchanged by any operation,  $\chi_R = U_R(\pm 1 + 2\cos\phi_R)$  with + for proper rotation and - for improper rotation and  $\Xi = (U_C - 2) \times (1 + 2\cos\phi)$  or  $\Xi = U_S(-1 + 2\cos\theta)$ . From the selection rules the frequencies in species  $A_1$ ,  $B_1$  and  $B_2$  are infra-red active;  $A_1$ ,  $A_2$ ,  $B_1$  and  $B_2$  are Raman active. The Raman lines in  $A_1$  are polarized; those in  $A_2$ ,  $B_1$  and  $B_2$  are depolarized.

From the relation

$$a^{(k)} = \frac{1}{h} \left\{ \sum_C (U_C - 2)(1 + 2\cos\phi) \chi^{(k)} + \sum_S U_S (-1 + 2\cos\theta) \chi^{(k)} \right\} \quad (1)$$

the number of frequencies in each species may be calculated<sup>34</sup>.

Applying this gives the following results

$$a^{(1)} = \frac{1}{4}(24 + 2 + 10) = 9 \quad (2)$$

$$a^{(2)} = \frac{1}{4}(24 - 2 - 10) = 3 \quad (3)$$

$$a^{(3)} = \frac{1}{4}(24 + 2 - 10) = 4 \quad (4)$$

$$a^{(4)} = \frac{1}{4}(24 - 2 + 10) = 8 \quad (5)$$

When the symmetry operations are applied to the molecule together with the character sign (either symmetric



or antisymmetric) from the character table and the conditions that the center of mass shall be fixed and the angular momentum shall be zero, the following cartesian coordinates are the only ones that remain for each species:

$$A_1: z_1, z_2, z_\alpha, z_\theta, y_1, y_2, y_\alpha, y_\theta, y_\gamma$$

$$A_2: x_1, x_2, x_\alpha, x_\theta$$

$$B_1: z_1, z_2, z_\alpha, z_\theta, y_1, y_2, y_\alpha, y_\theta$$

$$B_2: x_1, x_2, x_\alpha.$$

The only vibrations which will be considered are in-plane vibrations; hence, species  $A_2$  and  $B_2$  will give no frequencies since these vibrations are out of the plane.

## 2. The Potential Function

The force field which was chosen for this determination was the valence type force field. Thus the changes in bond length and changes in the bond angles were chosen as the coordinates for the potential function. The kinetic energy expression can be written directly in cartesian coordinates as

$$2T = M(\dot{x}_i^2 + \dot{y}_i^2 + \dot{z}_i^2) + m(\dot{x}_j^2 + \dot{y}_j^2 + \dot{z}_j^2), \quad i = 1 \text{ to } 4, \quad j = \alpha, \theta, \gamma, \delta, \sigma, \eta \quad (1)$$

The potential energy in symmetry coordinates is

$$\begin{aligned} 2V = & K_{12} |\Delta r_{12}|^2 + K_{23} |\Delta r_{23}|^2 + K_{34} |\Delta r_{34}|^2 + K_{\alpha 1} |\Delta r_{\alpha 1}|^2 \\ & + K_{\theta 1} |\Delta r_{\theta 1}|^2 + K_{\delta 2} |\Delta r_{\delta 2}|^2 + K_{\sigma 3} |\Delta r_{\sigma 3}|^2 + K_{\eta 4} |\Delta r_{\eta 4}|^2 \\ & + K_{\eta 4} |\Delta r_{\eta 4}|^2 + K_{\theta 1} |\Delta \theta_1|^2 + K_{\theta 2} |\Delta \theta_2|^2 + K_{\phi_1} |\Delta \phi_1|^2 \\ & + K_{\phi_2} |\Delta \phi_2|^2 + K_{\phi_3} |\Delta \phi_3|^2 + K_{\phi_4} |\Delta \phi_4|^2 + K_{\phi_5} |\Delta \phi_5|^2 \end{aligned}$$

(2)



$$+k\phi_6 |\Delta\phi_6|^2 + k\phi_7 |\Delta\phi_7|^2 + k\phi_8 |\Delta\phi_8|^2 + k\phi_9 |\Delta\phi_9|^2 + k\phi_{10} |\Delta\phi_{10}|^2.$$

The values of  $|\Delta r_{12}|^2$ ,  $|\Delta r_{23}|^2$ , ... are determined by taking the vector difference of the distances between two atoms in the rest position and when they have been given a small arbitrary displacement. These are

$$|\Delta r_{\alpha 1}|^2 = \left\{ \sqrt{(x_1 - x_\alpha)^2 + (y_1 - y_\alpha - d)^2 + (z_1 - z_\alpha + e)^2} - |r_{\alpha 1}^0| \right\}^2$$

$$|\Delta r_{\beta 1}|^2 = \left\{ \sqrt{(x_1 - x_\beta)^2 + (y_1 - y_\beta + f)^2 + (z_1 - z_\beta)^2} - |r_{\beta 1}^0| \right\}^2$$

$$|\Delta r_{12}|^2 = \left\{ \sqrt{(x_2 - x_1)^2 + (y_2 - y_1 + a)^2 + (z_2 - z_1 + b)^2} - |r_{12}^0| \right\}^2$$

$$|\Delta r_{22}|^2 = \left\{ \sqrt{(x_2 - x_2)^2 + (y_2 - y_2 + g)^2 + (z_2 - z_2 - h)^2} - |r_{22}^0| \right\}^2$$

$$|\Delta r_{23}|^2 = \left\{ \sqrt{(x_3 - x_2)^2 + (y_3 - y_2 + c)^2 + (z_3 - z_2)^2} - |r_{23}^0| \right\}^2$$

$$|\Delta r_{53}|^2 = \left\{ \sqrt{(x_3 - x_5)^2 + (y_3 - y_5 - g)^2 + (z_3 - z_5 - h)^2} - |r_{53}^0| \right\}^2$$

$$|\Delta r_{34}|^2 = \left\{ \sqrt{(x_4 - x_3)^2 + (y_4 - y_3 + a)^2 + (z_4 - z_3 - b)^2} - |r_{34}^0| \right\}^2$$

$$|\Delta r_{54}|^2 = \left\{ \sqrt{(x_4 - x_5)^2 + (y_4 - y_5 - f)^2 + (z_4 - z_5)^2} - |r_{54}^0| \right\}^2$$

$$|\Delta r_{24}|^2 = \left\{ \sqrt{(x_4 - x_2)^2 + (y_4 - y_2 + d)^2 + (z_4 - z_2 + e)^2} - |r_{24}^0| \right\}^2$$

$$|\Delta\theta_1|^2 = \frac{1}{\sin^2\theta_1^0} \left\{ - \frac{[(x_2 - x_1)(x_3 - x_2) + (y_2 - y_1 + a)(y_3 - y_2 + c) + (z_2 - z_1 + b)(z_3 - z_2)]}{\left[ \sqrt{(x_2 - x_1)^2 + (y_2 - y_1 + a)^2 + (z_2 - z_1 + b)^2} \right] \left[ \sqrt{(x_3 - x_2)^2 + (y_3 - y_2 + c)^2 + (z_3 - z_2)^2} \right]} - \cos\theta_1^0 \right\}^2$$

$$|\Delta\theta_2^0|^2 = \frac{1}{\sin^2\theta_2^0} \left\{ - \frac{[(x_3 - x_2)(x_4 - x_3) + (y_3 - y_2 + c)(y_4 - y_3 + a) + (z_3 - z_2)(z_4 - z_3 - b)]}{\left[ \sqrt{(x_3 - x_2)^2 + (y_3 - y_2 + c)^2 + (z_3 - z_2)^2} \right] \left[ \sqrt{(x_4 - x_3)^2 + (y_4 - y_3 + a)^2 + (z_4 - z_3 - b)^2} \right]} - \cos\theta_2^0 \right\}^2$$

$$|\Delta\phi_1|^2 = \frac{1}{\sin^2\phi_1^0} \left\{ - \frac{(x_1 - x_\alpha)(x_2 - x_1)(y_1 - y_\alpha - d)(y_2 - y_1 + a) + (z_1 - z_\alpha + e)(z_2 - z_1 + b)}{\left[ \sqrt{(x_1 - x_\alpha)^2 + (y_1 - y_\alpha - d)^2 + (z_1 - z_\alpha + e)^2} \right] \left[ \sqrt{(x_2 - x_1)^2 + (y_2 - y_1 + a)^2 + (z_2 - z_1 + b)^2} \right]} - \cos\phi_1^0 \right\}^2$$



$$|\Delta\phi_2|^2 = \frac{1}{\sin^2\phi_2^0} \left\{ \frac{[(x_1-x_a)(x_1-x_b) + (y_1-y_d-d)(y_1-y_e+f) + (z_1-z_d+e)(z_1-z_e)]}{\sqrt{[(x_1-x_a)^2 + (y_1-y_d-d)^2 + (z_1-z_d+e)^2]} \sqrt{[(x_1-x_b)^2 + (y_1-y_e+f)^2 + (z_1-z_e)^2]}} - \cos\phi_2^0 \right\}^2$$

$$|\Delta\phi_3|^2 = \frac{1}{\sin^2\phi_3^0} \left\{ \frac{[(x_1-x_b)(x_2-x_1) + (y_1-y_e+f)(y_2-y_1+a) + (z_1-z_e)(z_2-z_1+b)]}{\sqrt{[(x_1-x_b)^2 + (y_1-y_e+f)^2 + (z_1-z_e)^2]} \sqrt{[(x_2-x_1)^2 + (y_2-y_1+a)^2 + (z_2-z_1+b)^2]}} - \cos\phi_3^0 \right\}^2$$

$$|\Delta\phi_4|^2 = \frac{1}{\sin^2\phi_4^0} \left\{ \frac{[(x_2-x_b)(x_2-x_1) + (y_2-y_e+f)(y_2-y_1+a) + (z_2-z_e-h)(z_2-z_1+b)]}{\sqrt{[(x_2-x_b)^2 + (y_2-y_e+f)^2 + (z_2-z_e-h)^2]} \sqrt{[(x_2-x_1)^2 + (y_2-y_1+a)^2 + (z_2-z_1+b)^2]}} - \cos\phi_4^0 \right\}^2$$

$$|\Delta\phi_5|^2 = \frac{1}{\sin^2\phi_5^0} \left\{ \frac{[(x_2-x_b)(x_3-x_2) + (y_2-y_e+f)(y_3-y_2+c) + (z_2-z_e-h)(z_3-z_2)]}{\sqrt{[(x_2-x_b)^2 + (y_2-y_e+f)^2 + (z_2-z_e-h)^2]} \sqrt{[(x_3-x_2)^2 + (y_3-y_2+c)^2 + (z_3-z_2)^2]}} - \cos\phi_5^0 \right\}^2$$

$$|\Delta\phi_6|^2 = \frac{1}{\sin^2\phi_6^0} \left\{ \frac{[(x_3-x_b)(x_3-x_2) + (y_3-y_e+f)(y_3-y_2+c) + (z_3-z_e-h)(z_3-z_2)]}{\sqrt{[(x_3-x_b)^2 + (y_3-y_e+f)^2 + (z_3-z_e-h)^2]} \sqrt{[(x_3-x_2)^2 + (y_3-y_2+c)^2 + (z_3-z_2)^2]}} - \cos\phi_6^0 \right\}^2$$

$$|\Delta\phi_7|^2 = \frac{1}{\sin^2\phi_7^0} \left\{ \frac{[(x_3-x_b)(x_4-x_3) + (y_3-y_e+f)(y_4-y_3+a) + (z_3-z_e-h)(z_4-z_3-h)]}{\sqrt{[(x_3-x_b)^2 + (y_3-y_e+f)^2 + (z_3-z_e-h)^2]} \sqrt{[(x_4-x_3)^2 + (y_4-y_3+a)^2 + (z_4-z_3-h)^2]}} - \cos\phi_7^0 \right\}^2$$

$$|\Delta\phi_8|^2 = \frac{1}{\sin^2\phi_8^0} \left\{ \frac{[(x_4-x_b)(x_4-x_3) + (y_4-y_e+f)(y_4-y_3+a) + (z_4-z_e-h)(z_4-z_3-h)]}{\sqrt{[(x_4-x_b)^2 + (y_4-y_e+f)^2 + (z_4-z_e-h)^2]} \sqrt{[(x_4-x_3)^2 + (y_4-y_3+a)^2 + (z_4-z_3-h)^2]}} - \cos\phi_8^0 \right\}^2$$

$$|\Delta\phi_9|^2 = \frac{1}{\sin^2\phi_9^0} \left\{ \frac{[(x_4-x_b)(x_4-x_n) + (y_4-y_e+f)(y_4-y_n+d) + (z_4-z_e-h)(z_4-z_n+e)]}{\sqrt{[(x_4-x_b)^2 + (y_4-y_e+f)^2 + (z_4-z_e-h)^2]} \sqrt{[(x_4-x_n)^2 + (y_4-y_n+d)^2 + (z_4-z_n+e)^2]}} - \cos\phi_9^0 \right\}^2$$

$$|\Delta\phi_{10}|^2 = \frac{1}{\sin^2\phi_{10}^0} \left\{ \frac{[(x_4-x_n)(x_4-x_3) + (y_4-y_n+d)(y_4-y_3+a) + (z_4-z_n+e)(z_4-z_3-h)]}{\sqrt{[(x_4-x_n)^2 + (y_4-y_n+d)^2 + (z_4-z_n+e)^2]} \sqrt{[(x_4-x_3)^2 + (y_4-y_3+a)^2 + (z_4-z_3-h)^2]}} - \cos\phi_{10}^0 \right\}^2$$



### 3. Calculation of the Vibrational Frequencies

Now from the application of group theory we have that for species  $A_1$  all X's are zero and

$$\begin{aligned} z_4 = z_1, z_3 = z_2, z_7 = z_2, z_8 = z_2, \\ y_4 = y_1, y_3 = -y_2, y_7 = -y_2, y_8 = -y_2, \end{aligned}$$

and 
$$z_5 = z_8 = -\frac{M}{m} z_1 - \frac{M}{m} z_2 - z_2 - z_2. \quad (3)$$

For species  $B_1$  all X's are zero and

$$z_4 = -z_1, z_3 = -z_2, z_7 = -z_2, z_8 = -z_2,$$

$$y_4 = y_1, y_3 = y_2, y_7 = y_2, y_8 = y_2$$

$$y_8 = y_8 = -\frac{M}{m} y_1 - \frac{M}{m} y_2 - y_2 - y_2,$$

and 
$$-z_5 = z_8 = \Omega y_1 + \kappa y_2 + \rho y_2 + \lambda y_2 - \nu z_1 - \chi z_2 - \xi z_2 - \xi z_2 \quad (4)$$

where the constants have the following values:

$$\kappa = \frac{2Mh}{m(2g+c)}, \quad \lambda = \frac{2(b+h)}{2g+c}, \quad \rho = \frac{2(b+l+h)}{2g+c},$$

$$\xi = \frac{2a+2f+c}{2g+c}, \quad \eta = \frac{2a-2d+c}{2g+c}, \quad \chi = \frac{Mc}{m(2g+c)},$$

$$\Omega = \frac{2M(b+h)}{m(2g+c)}, \quad \nu = \frac{M(2a+c)}{m(2g+c)}$$

These substitutions are made in the expressions given for the symmetry coordinates and these are then expanded in a Taylor's series leaving only second order terms. The final expressions are then substituted into the potential energy expression given previously and the coefficients of the cartesian coordinates are grouped together giving the constants  $b_{ij}$  in the secular equation

$$\left| b_{ij} - \lambda a_{ij} \right| = 0. \quad (5)$$

The constants  $A_{ij}$  are similarly obtained by applying the symmetry conditions above to the kinetic energy expression and grouping the coefficients of the cartesian coordinates.



The constants can now be evaluated numerically and substituted into the secular equation. The values for the constants that were used throughout this work are given in Table II. The masses of the atoms were taken from Birge's<sup>35</sup> table of values of physical constants. The values for the force constants were transferred from the work by Wilson and Wells<sup>36</sup> on propylene and the paper by Crawford and Brinkley<sup>37</sup> on force constants in organic molecules.

Table II

$$\begin{aligned}
 M &= 19.93 \times 10^{-24} \text{ gm} \\
 m &= 1.673 \times 10^{-24} \text{ gm} \\
 \theta_1^{\circ} &= \theta_2^{\circ} = \phi_1^{\circ} \rightarrow \phi_{10}^{\circ} = 120^{\circ} \\
 r_{12}^{\circ} &= r_{34}^{\circ} = 1.35 \times 10^{-8} \text{ cm} \\
 r_{23}^{\circ} &= 1.44 \times 10^{-8} \text{ cm} \\
 r_{21}^{\circ} &\rightarrow r_{14}^{\circ} = 1.09 \times 10^{-8} \text{ cm}
 \end{aligned}$$

$$\begin{aligned}
 k_{12} &= k_{34} = 9.72 \times 10^5 \text{ dynes/cm} \\
 k_{23} &= 4.50 \times 10^5 \text{ dynes/cm} \\
 k_{21} &\rightarrow k_{14} = 4.79 \times 10^5 \text{ dynes/cm} \\
 k_{\theta_1} &= k_{\theta_2} = 1.20 \times 10^{-11} \text{ dyne cm/rad}^2 \\
 k_{\phi_1} &= k_{\phi_3} = k_{\phi_4} = k_{\phi_7} = k_{\phi_8} = k_{\phi_{10}} \\
 &= 0.939 \times 10^{-11} \text{ dyne cm/rad}^2 \\
 k_{\phi_2} &= k_{\phi_9} = 0.535 \times 10^{-11} \text{ dyne cm/rad}^2 \\
 k_{\phi_5} &= k_{\phi_6} = 0.654 \times 10^{-11} \text{ dyne cm/rad}^2
 \end{aligned}$$

This gives two secular equations, one of eighth order and one of ninth order. The expansion of secular equations of this size is a laborious task, and usually approximations of various kinds or iteration schemes are used for solving them. A very powerful method for an exact expansion of determinants of this type which was used in this work will now be described.

35. Birge, R.T., Rev. Mod. Phys. 13, 233 (1941)  
 36. Wilson, E.B., Jr. and Wells, A.J., J. Chem. Phys. 9, 314 (1941)  
 37. Crawford, B.L., Jr. and Brinkley, S.R., Jr., J. Chem. Phys. 9, 69, (1941)



(a) An Exact Method for Expanding the Secular

Equation - The method here described is due to J. G. Bryan<sup>38</sup> who devised the method to permit an exact expansion of the characteristic equation and latent vectors of a matrix. The characteristic equation is defined by

$$|A - \lambda I| = 0 \quad (6)$$

where I is the unit matrix. The process of expanding this equation consists of building an auxiliary matrix and row vector from the original matrix A.

A vector  $f_1$  is built as follows

$$f_1 = -1 \quad a_{11} \cdot \quad (7)$$

This vector is then used as the basis for building the auxiliary matrix  $B_2$ . A matrix  $A_2$  is written down first which is composed of the first two elements of the first two rows of A. This is divided into two parts with the last row being indicated by  $a_2$  and the first row by  $\alpha$ . Thus

$$A_2 = \begin{array}{cc} \frac{a_{11}}{a_{21}} & \frac{a_{12}}{a_{22}} \\ \alpha & a_2 \end{array} \quad (8)$$

The auxiliary matrix  $B_2$  is then built by first writing down the vector  $f_1$ . The first row is built by multiplying  $\alpha$  in  $A_2$  times a null column for the first term, and then multiplying  $\alpha$  times this first column so built for the second term. Thus

$$\begin{array}{cc} B_2 = 0 & -a_{12} \\ f_1 = -1 & a_{11} \end{array} \quad (9)$$

38. Bryan, J. G., A Method for the Exact Determination of the Characteristic Equation and Latent Vectors of a Matrix with Applications to the Discriminant Function for More than Two Groups. Harvard Graduate School of Education Dissertation (1950)



The process is then repeated by writing down the first three terms from the first three rows of the original matrix for  $A_3$ . That is

$$A_3 = \begin{array}{ccc} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{array} \begin{array}{l} \alpha \\ \\ a_3 \end{array} \quad (10)$$

where the last row is now designated by  $a_3$  and the remaining rows are designated by  $\alpha$ . The vector  $f_2$  is now built by multiplying  $a_2$  by the null column in  $B_2$  and  $f_1$  and subtracting the next number in  $f_1$ , that is, -1 for the first term of  $f_2$ . The second term is then obtained by multiplying  $a_2$  by the first column of  $B_2$  and  $f_1$  and subtracting the next term in  $f_1$ . The last term is obtained by multiplying  $a_2$  times the last column in  $B_2$  and  $f_1$ . Thus

$$f_2 = 1 - (a_{22} \ a_{11}) \ a_{11} \ a_{22} \quad (11)$$

The matrix  $B_3$  is then built in the same manner as  $B_2$  was. First  $f_2$  is written down and then the first term of the first column of  $B_3$  is obtained by multiplying the first row of  $\alpha$  in  $A_3$  by the null column in  $B_3$  and  $f_2$ . The second term in the column is similarly obtained by multiplying the second row in  $\alpha$  by the null column. Thus there will always be a column of zeros as the first column in the auxiliary matrix. The first and second terms of the second column in  $B_3$  are then obtained similarly by multiplying this first column of  $B_3$  and  $f_2$  by the first row of  $\alpha$  in  $A_3$  for the first term and by the second



row of  $\alpha$  for the second term. The last column in  $B_3$  is similarly obtained. The vector  $f_3$  is obtained in the same manner as  $f_2$  and the entire process is continued until the entire matrix has been written down as  $A_n$ . The coefficients of the expanded characteristic equation will then be given by the terms in  $f_n$  which is obtained in the manner described above by multiplying  $a_n$  by the columns of  $B_n$  and  $f_{n-1}$  and subtracting the next term in  $f_{n-1}$ .

There are several advantages to this method besides the obvious advantage of permitting an exact expansion of the characteristic equation with even less labor than is involved in previous approximation methods. One of these is the fact that the method is readily adaptable to use by I.B.M. computing machines or hand computing machines. The other is the fact that there is a continuous check on the work that has been performed. The check is obtained by summing the columns of  $\alpha$  and multiplying this row of sums times the columns of  $B_i$  and  $f_{i-1}$  that is being built by this particular  $\alpha$ . The product of this row of sums of  $\alpha$  in some  $A_i$  times a given column in  $B_i$  and  $f_{i-1}$  must equal the sum of the terms in the next column of  $B_i$ . Furthermore, once  $B_i$  has been completed the product of any row in  $\alpha$  times the last column in  $B_i$  and  $f_{i-1}$  must equal zero. An example will probably serve best to clarify the operations involved. Consider the matrix

$$\begin{vmatrix} 2-\lambda & -1 & -4 \\ 4 & 3-\lambda & 2 \\ -2 & 3 & 1-\lambda \end{vmatrix} = 0.$$



This can be written as

$$\begin{vmatrix} 2 & -1 & -4 \\ 4 & 3 & 2 \\ -2 & 3 & 1 \end{vmatrix} - \lambda \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} = 0$$

where the first matrix is the matrix A in our previous discussion. Then

$$f_1 = -1 \quad 2$$

and

$$\begin{array}{r} A_2 \\ \text{Sum} \end{array} \quad \begin{array}{r} \frac{2}{4} \quad \frac{-1}{3} \\ (\alpha) \quad 2 \quad -1 \end{array} \quad \begin{array}{l} \alpha \\ a_2 \end{array}$$

$$\begin{array}{r} \text{Sum} \\ \text{Check} \end{array} \quad \begin{array}{r} B_2 \\ f_1^2 \\ (B_2^1) \\ 2 \end{array} \quad \begin{array}{r} \frac{0}{-1} \quad \frac{1}{2} \\ 0 \quad 1 \\ 0 \quad 1 \end{array} \quad \begin{array}{l} | \\ 0 \end{array}$$

$$\begin{array}{r} \text{Sum} \end{array} \quad \begin{array}{r} A_3 \\ (\alpha) \end{array} \quad \begin{array}{r} \frac{2}{4} \quad \frac{-1}{3} \quad \frac{-4}{2} \\ -2 \quad 3 \quad 1 \\ 6 \quad 2 \quad -2 \end{array} \quad \begin{array}{l} \alpha \\ a_3 \end{array}$$

$$\begin{array}{r} \text{Sum} \\ \text{Check} \end{array} \quad \begin{array}{r} B_3 \\ f_2^2 \\ (B_3^2) \\ 3 \end{array} \quad \begin{array}{r} \frac{0}{0} \quad \frac{-4}{2} \quad \frac{10}{-20} \\ 1 \quad -5 \quad 10 \\ 0 \quad -2 \quad -10 \\ 0 \quad -2 \quad -10 \end{array} \quad \begin{array}{l} | \\ 0 \\ 0 \end{array}$$

$$f_3 = -1 \quad 6 \quad -1 \quad -70$$

Thus the expanded characteristic equation in

$$\lambda^3 - 6\lambda^2 + \lambda + 70 = 0.$$

Now the secular equation considered in this work is in general not in the form of the characteristic equation but by proper addition and subtraction of rows and columns and then division of each column by the coefficient of  $\lambda$  in that column after there are  $\lambda$ 's only on the principal diagonal it can be put into the proper form. Then the pro-



cess described can be used to obtain the expanded secular equation. As a further example, the entire solution of the eighth order secular equation is presented. The original secular equation is as follows:

<p style="text-align: center;">1.</p> <p>2585.223001 - <math>\lambda</math>919.445462  1566.097331 - <math>\lambda</math>533.133809  285.972608 - <math>\lambda</math>100.388702  211.339583 - <math>\lambda</math> 75.544711  -1261.519224 + <math>\lambda</math>437.160272  -749.750371 + <math>\lambda</math>225.631124  -63.368231 + <math>\lambda</math> 22.370756  -188.782090 + <math>\lambda</math> 65.401606</p>	<p style="text-align: center;">2.</p> <p>1566.097331 - <math>\lambda</math>533.133809  1031.210323 - <math>\lambda</math>389.394129  172.922857 - <math>\lambda</math> 55.872969  132.222504 - <math>\lambda</math> 44.774624  -708.579705 + <math>\lambda</math>195.288892  -413.541948 + <math>\lambda</math>100.794274  -35.941267 + <math>\lambda</math> 9.993498  -106.436015 + <math>\lambda</math> 29.216303</p>
---	---

<p style="text-align: center;">3.</p> <p>285.972608 - <math>\lambda</math>100.388702  172.922857 - <math>\lambda</math> 55.872969  34.489040 - <math>\lambda</math> 13.123452  24.163362 - <math>\lambda</math> 8.431028  -141.764534 + <math>\lambda</math> 53.115492  -85.888794 + <math>\lambda</math> 27.414450  -9.308504 + <math>\lambda</math> 2.718074  -21.970341 + <math>\lambda</math> 7.946372</p>	<p style="text-align: center;">4.</p> <p>211.339583 - <math>\lambda</math> 75.544711  132.222504 - <math>\lambda</math> 44.774624  24.163362 - <math>\lambda</math> 8.431028  22.942814 - <math>\lambda</math> 8.018383  -105.753050 + <math>\lambda</math> 36.714398  -62.626083 + <math>\lambda</math> 18.949368  -5.412186 + <math>\lambda</math> 1.878782  -15.822713 + <math>\lambda</math> 5.492679</p>
--	---

<p style="text-align: center;">5.</p> <p>-1261.519244 + <math>\lambda</math>437.160272  -708.579705 + <math>\lambda</math>195.288892  -141.764534 + <math>\lambda</math> 53.115492  -105.753050 + <math>\lambda</math> 36.714398  695.144505 - <math>\lambda</math>308.527845  397.096281 - <math>\lambda</math>148.953422  30.793178 - <math>\lambda</math> 14.768355  99.841587 - <math>\lambda</math> 43.175750</p>	<p style="text-align: center;">6.</p> <p>-749.750371 + <math>\lambda</math>225.631124  -413.541948 + <math>\lambda</math>100.794274  -85.888794 + <math>\lambda</math> 27.414450  -62.626083 + <math>\lambda</math> 18.949368  397.096281 - <math>\lambda</math>148.953422  254.216094 - <math>\lambda</math> 96.809801  20.538526 - <math>\lambda</math> 7.622377  60.830535 - <math>\lambda</math> 22.284260</p>
--	--

<p style="text-align: center;">7.</p> <p>-63.358231 + <math>\lambda</math> 22.370756  -35.941267 + <math>\lambda</math> 9.993498  -9.308504 + <math>\lambda</math> 2.718073  -5.412186 + <math>\lambda</math> 1.878782  30.793178 - <math>\lambda</math> 14.768355  20.538526 - <math>\lambda</math> 7.622377  5.676052 - <math>\lambda</math> 2.429588  5.409625 - <math>\lambda</math> 2.209429</p>	<p style="text-align: center;">8.</p> <p>-188.782090 + <math>\lambda</math> 65.401606  -106.436015 + <math>\lambda</math> 29.216303  -21.970341 + <math>\lambda</math> 7.946372  -15.822713 + <math>\lambda</math> 5.492679  99.841587 - <math>\lambda</math> 43.175750  60.830535 - <math>\lambda</math> 22.284260  5.409625 - <math>\lambda</math> 2.209429  16.397630 - <math>\lambda</math> 8.133182</p>
---	--

# 0



After adding and subtracting rows and columns until the terms in  $\lambda$  remained only on the diagonal and then dividing each column by the coefficient of  $\lambda$  in the column, the following matrix resulted:

1.	2.	3.	4.	
2.067366- $\lambda$	.297095	.631730	.283279	
.260648	1.510432- $\lambda$	.135973	.236602	
1.056297	.259149	2.419432- $\lambda$	-.392156	
.893082	.850230	-.739404	2.311303- $\lambda$	
-.212079	.174022	.121093	-.112740	
-.170916	-.274173	.113293	-1.208686	
.475468	-.932967	-.026247	-.595243	
-.165267	.206441	.033435	.017732	
5.	6.	7.	8.	
-.337603	-.044726	.641858	-2.341203	} = 0
.243037	-.062945	-1.104950	2.565703	
.322316	.049572	-.059245	.791970	
-.565803	-.997172	-2.533311	.791960	
.829401- $\lambda$	-.155567	-1.110603	1.815131	
-.946340	1.900935- $\lambda$	5.451680	-.408514	
-1.309634	1.056800	6.498104- $\lambda$	-3.943537	
.203969	-.007546	-.375795	2.082605- $\lambda$	

This can now be expanded by the method outlined above. Then

$$f_1 = -1 \quad 2.067366$$

$$A_2 \begin{array}{l} \frac{2.067366}{.260648} \end{array} \begin{array}{l} .297095 \\ 1.510432 \end{array} \begin{array}{l} \alpha \\ a_2 \end{array}$$

$$B_2 \begin{array}{l} 0 \\ -1 \end{array} \begin{array}{l} -.297095 \\ 2.067366 \end{array}$$

$$A_3 \begin{array}{l} \frac{2.067366}{.260648} \\ 1.056297 \end{array} \begin{array}{l} .297095 \\ 1.510432 \\ .259149 \end{array} \begin{array}{l} .631740 \\ .135973 \\ 2.419432 \end{array} \begin{array}{l} \alpha \\ a_3 \end{array}$$

$$\text{Sum } (\alpha) \begin{array}{l} 2.328014 \\ 1.807527 \\ .767703 \end{array}$$

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	0	.631730	-.913788
B <sub>3</sub>	0	.135973	-.116447
f <sub>2</sub>	1	-3.577798	3.045179

Sum (B <sub>3</sub> )	0	.767703	-1.030235
Check	0	.767703	-1.030235

	2.067366	.297095	.631740	.283279	
	.260648	1.510432	.135973	.236602	α
A <sub>4</sub>	1.056297	.259149	2.419432	-.392156	
	.893082	.850230	-.739404	2.311303	a <sub>4</sub>

Sum (α)	3.384311	2.066676	3.187135	.127725
---------	----------	----------	----------	---------

	0	-.283279	1.290691	-1.252243
B <sub>4</sub>	0	-.236602	1.041072	-.933276
	0	.392156	-1.763597	1.679522
f <sub>3</sub>	-1	5.997230	-10.998886	6.372195

Sum(B <sub>4</sub> )	0	-.127725	.568166	-.505997
Check <sup>4</sup>	0	-.127725	.568166	-.505996

	2.067366	.297095	.631730	.283279	-.337603
	.260648	1.510432	.135973	.236602	.243037
A <sub>5</sub>	1.056297	.259149	2.419432	-.392156	.322316
	.893082	.850230	-.739404	2.311303	-.565803
	-.212079	.174022	.121093	-.112740	.829401
					a <sub>5</sub>

Sum (α)	4.277393	2.916906	2.447731	2.439028	-.338053
---------	----------	----------	----------	----------	----------

	0	-.337603	2.222578	-4.468156	2.593151
B <sub>5</sub>	0	.243037	-1.830229	4.132162	-2.446678
	0	.322316	-1.969895	3.680384	-2.076983
	0	-.565803	3.060059	-4.686908	2.066986
f <sub>4</sub>	1	-8.308533	24.116182	-28.452099	11.574373

Sum(B <sub>5</sub> )	0	-.338053	1.482514	-1.342518	.136476
Check <sup>5</sup>	0	-.338053	1.482513	-1.342518	.136477

	2.067366	.297095	.631730	.283279	-.337603	-.044726
	.260648	1.510432	.135973	.236602	.243037	-.062945
A <sub>6</sub>	1.056297	.259149	2.419432	-.392156	.322316	.049572
	.893082	.850230	-.739404	2.311303	-.565803	-.997172
	-.212079	.174022	.121093	-.112740	.829401	-.155567
	-.170916	-.274173	.113293	-1.208686	-.946340	1.900935
						a <sub>6</sub>

Sum(α)	4.065314	3.090928	2.568824	2.326288	.491348	-1.210838
--------	----------	----------	----------	----------	---------	-----------



	0	.044726	-.098896	-.292578	.534401	-.087166
	0	.062945	-.201454	-.327598	1.299894	-.738005
$B_6$	0	-.049572	.055700	.650466	-1.179141	.381805
	0	.997172	-6.765230	15.563708	-14.472034	4.480598
	0	.155567	-1.409489	4.376339	-5.365307	2.212552
$f_5$	-1	9.137934	-30.790576	47.080691	-32.531812	8.139528
Sum( $\theta$ )	0	1.210838	-8.419369	19.970337	-19.182187	6.249784
Check	0	1.210838	-8.419369	19.970337	-19.182188	6.249783

		2.067366	.297095	.631730	.283279	.337603
		.260648	1.510432	.135973	.236602	.243037
$A_7$		1.056297	.259149	2.419432	-.392156	.322316
		.893082	.850230	-.739404	2.311303	-.565803
		-.212079	.174022	.121093	-.112740	.829401
		-.170916	-.274173	.113293	-1.208686	-.946340
		.475468	-.932967	-.026247	-.595243	-1.309634

					.044726	.641858
					-.062945	-1.104950
					.049572	-.059245
					-.997172	-2.533311
					-.155567	-1.110603
					1.900935	5.451680
					1.056800	6.498104
Sum( $\alpha$ )	3.894398	2.816755	2.682117	1.117602	-.454992	
				.690097	1.285429	

	0	.641858	-6.710656	23.429747	-32.789724	
	0	-1.104950	9.475230	-29.459247	40.224360	
	0	-.059245	1.808043	-8.579664	12.915582	
$B_7$	0	-2.533311	16.979335	-39.051691	38.467198	
	0	-1.110603	10.440585	-34.834754	49.730319	
	0	5.451680	-45.517575	136.844683	-180.082491	
$f_6$	1	-11.038869	46.778189	-96.022233	99.289523	

					18.213245	-3.312372
					-23.221188	4.395140
					-6.828934	1.160792
					-15.820024	2.298122
					-29.828843	5.830528
					101.452143	-18.954283
					-47.992160	8.223746
Sum( $B_7$ )	1.285429	-13.525038	48.349074	-71.534756		
				43.966399	-8.582073	
Check	1.285429	-13.525037	48.349074	-71.534755		
				43.966399	-8.582073	



	2.067366	.297095	.631730	.283279	-.337603	
	.260648	1.510432	.135973	.236602	.243037	
A <sub>8</sub>	1.056297	.259149	2.419432	-.392156	.322316	
	.893082	.850230	.739404	2.311303	-.565703	
	-.212079	.174022	.121093	-.112740	.829401	
	-.170916	-.274173	.113293	-1.208686	.946340	
	.475468	-.932967	-.026247	-.595243	-1.309634	
	<u>-.165267</u>	<u>.206441</u>	<u>.033435</u>	<u>.017732</u>	<u>.203969</u>	
			-.044726	.641858	-2.341203	
			-.062945	-1.104950	2.565703	
			.049572	-.059245	.791970	
			-.997172	-2.533311	.791960	α
			-.155567	-1.110603	1.815131	
			1.900935	5.451680	-.408514	
			<u>1.056800</u>	<u>6.498104</u>	<u>3.943537</u>	
			<u>-.007546</u>	<u>-.375795</u>	<u>2.082605</u>	a <sub>8</sub>
Sum(α)	4.369866	1.883788	2.655870	.522359	-1.764626	
			1.746897	7.783533	-.728490	
C	2.341203	-34.578691	169.794569	-368.924785		
0	2.565703	36.610239	-183.896618	405.450890		
0	-.791970	13.292887	-70.908184	166.565841		
B <sub>8</sub>	0	-.791960	3.182598	-27.136810	145.839614	
0	-1.815131	24.933551	-123.227256	285.384102		
0	.408514	17.999896	-151.753276	413.366798		
0	<u>3.943537</u>	<u>-36.724235</u>	<u>122.560845</u>	<u>-178.539182</u>		
f <sub>7</sub>	1.	17.536973	-108.448533	316.030387	-470.918704	
			377.377522	-170.460830	26.887299	
			-394.220247	163.557080	-22.645782	
			-188.719756	93.029443	-15.931958	
			-265.155967	180.066682	-40.977042	
			-331.574786	184.716806	-38.351770	
			-470.760675	241.720995	-47.787798	
			<u>115.150376</u>	<u>-30.148225</u>	<u>2.334004</u>	
			361.391323	-133.881886	18.698157	
Sum (B <sub>8</sub> )	0	.728490	24.716245	-264.566730	869.143278	
			-1157.903533	662.481951	-136.473047	
Check	0	.728490	24.716246	-264.566730	869.143278	
			-1157.903534	662.481952	-136.473049	
f <sub>8</sub>	1	-19.619578	142.158734	-509.361764	990.160760	
			-1067.116658	624.402846	-182.009395	
					+ 20.223912	

These are the coefficients of the expanded secular equation.



(b) The Determination of the Normal Frequencies -

The solution of the expanded equation, which was accomplished by Horner's method, yields the following eight roots:

$$.283785 \times 10^{29}, \quad .535005 \times 10^{29}, \quad .691997 \times 10^{29}, \quad 1.062514 \times 10^{29}$$

$$2.091375 \times 10^{29}, \quad 3.101651 \times 10^{29}, \quad 3.244094 \times 10^{29}, \quad 8.609156 \times 10^{29}$$

But these are equal to  $4\pi^2\nu_i^2$  where the  $\nu_i$  are the frequencies of vibration. Then solving for the wave numbers gives

$$\frac{1}{\lambda_1} = 894 \text{ cm}^{-1}, \quad \frac{1}{\lambda_2} = 1228 \text{ cm}^{-1},$$

$$\frac{1}{\lambda_3} = 1397 \text{ cm}^{-1}, \quad \frac{1}{\lambda_4} = 1731 \text{ cm}^{-1},$$

$$\frac{1}{\lambda_5} = 2428 \text{ cm}^{-1}, \quad \frac{1}{\lambda_6} = 2957 \text{ cm}^{-1},$$

$$\frac{1}{\lambda_7} = 3024 \text{ cm}^{-1}, \quad \frac{1}{\lambda_8} = 4926 \text{ cm}^{-1},$$

The expansion of the ninth order secular equation and the solution for the wave numbers by the same method as described above gives the following nine values:

$$\frac{1}{\lambda_1} = 434 \text{ cm}^{-1}, \quad \frac{1}{\lambda_2} = 1182 \text{ cm}^{-1}, \quad \frac{1}{\lambda_3} = 1324 \text{ cm}^{-1},$$

$$\frac{1}{\lambda_4} = 1642 \text{ cm}^{-1}, \quad \frac{1}{\lambda_5} = 1642 \text{ cm}^{-1}, \quad \frac{1}{\lambda_6} = 2062 \text{ cm}^{-1},$$

$$\frac{1}{\lambda_7} = 2846 \text{ cm}^{-1}, \quad \frac{1}{\lambda_8} = 2992 \text{ cm}^{-1}, \quad \frac{1}{\lambda_9} = 2994 \text{ cm}^{-1},$$

The values for  $\nu_4$ ,  $\nu_5$ ,  $\nu_8$  and  $\nu_9$  indicate degeneracy; however, these are not first order degeneracies. The pair of roots for  $\nu_4$  and  $\nu_5$  in the solution of the equation turned out to be just barely imaginary; that is, the curve just barely missed crossing the axis. A recheck of all of the

The following table shows the results of the experiment. The first column shows the number of trials, the second column shows the number of correct responses, and the third column shows the percentage of correct responses. The data is as follows:

10	7	70%	10	8	80%
20	14	70%	20	15	75%
30	21	70%	30	22	73%
40	28	70%	40	29	72%
50	35	70%	50	36	72%

The results of the experiment show that the percentage of correct responses is consistently high, ranging from 70% to 80%. This suggests that the subjects are able to perform the task accurately. The data is as follows:

10	7	70%	10	8	80%
20	14	70%	20	15	75%
30	21	70%	30	22	73%
40	28	70%	40	29	72%
50	35	70%	50	36	72%

The following table shows the results of the experiment. The first column shows the number of trials, the second column shows the number of correct responses, and the third column shows the percentage of correct responses. The data is as follows:

work showed that there did not seem to be an error which indicates that one or possibly more of the potential constants should probably be adjusted slightly. However, it may also be the case that these two pair of roots may be accidental degeneracies. The general grouping of the lines seems to check fairly well with observed spectra, as will be demonstrated later, so that these may very well be accidental degeneracies produced by interactions between vibrations.

#### 4. Comparison of Results with Observed Spectra

The observed frequencies for butadiene that are listed in Table III were obtained from results published by Rasmussen, Tunnicliff and Brattain<sup>39</sup>, Creitz and Smith<sup>40</sup>, Richards and Nielson<sup>41</sup>, and The American Petroleum Institute<sup>42</sup>. The calculated frequencies are listed in the adjacent column with matching between observed and calculated frequencies indicated. A comparison of observed and calculated spectra is also made in Fig. 2. As is apparent from the table and figure, there seems to be fairly good matching of the general distribution of the calculated lines with the observed.

So long as interaction between the end groups of atoms in the chain is not taken into consideration, as was

39. Rasmussen, Tunnicliff, and Brattain, Loc. Cit.

40. Creitz, E. C. and Smith, F. A., J. Res. Nat. Bu. Stand. 43, 365 (1949)

41. Richards, Charles M., and Nielsen, J. Reed, J. Op. Soc. Am. 40, 438 (1950)

42. Am. Petroleum Inst. Res. Proj. 44 at N.B.S. Cat. of Infra-red Spectrograms.



the case in the present work, the calculated frequencies will be the same for either the cis-or trans-form of the molecule. The only difference will be in the selection rules applying. Thus the  $C_{2h}$  point group was assumed as applying to the molecule since the selection rules with this assumption permitted better agreement between the more intense observed lines and calculated lines. The matching required between the calculated accidental degeneracies and observed lines indicates that the resonance has caused a rather large shift in the position of these observed lines.

TABLE III

Comparison of Calculated and Observed Frequencies, in Wave Numbers

Observed I.R.		Calculated
	Ra.	
	320 v.w.(?)	
	513 S. (P)	434 Ra
520		
	686 v.w.(?)	
909 v.v.S.		894 I.R.
	910 m(D)	
1014 v.s.		
	1205 vS(P)	1180 Ra
1282 m.	1279 vS(P)	1230 I.R.
	1302 S.(P)	1320 Ra
1374 S.		
1391 S.		1400 Ra
	1442 v.S.(P)	1640 Ra
1479 w.		
1497 w.		
1597 v.v.S.		
1608 v.v.S.		
	1643 v.v.S.(P)	1640 Ra
1759 w.		1730 I.R.
	1780 w(P)	
1812 m.		
1821 m.		
1969 w.		
	2092 v.w.(?)	2062 Ra
2495 w.		2430 I.R.
	2842 v.w.(?)	2846 Ra



TABLE III (Continued)

Observed		Calculated
	2879 vn.w(?)	
2981 w.		2960 I.R.
	3014 v.S.(P)	2990 Ra
3015 v.S.		3020 I.R.
3095 v.S.		
	3101 m(P)	2990 Ra
4938 w		4930 I.R.

The form of the normal vibrations can be determined<sup>43</sup> by substituting the corresponding value of  $\lambda$  in the secular equation and solving for the ratios of the coordinates which are equal to the ratios of the minors of any one row of the determinant. These ratios always remain equal during the oscillation of the particles for any one normal vibration. For  $\lambda_1$ , in species  $B_1$ , the ratios of the coordinates

$$y_1 : y_2 : y_\alpha : y_\beta : z_1 : z_2 : z_\alpha : z_\beta$$

were calculated to be in the ratios

$$\begin{aligned} &.171063: -.020901: -.155850: .950302: -.812493 \\ &: 1.039836: -.031805: -.108816 \end{aligned}$$

43. Herzberg, Op. Cit., p. 69



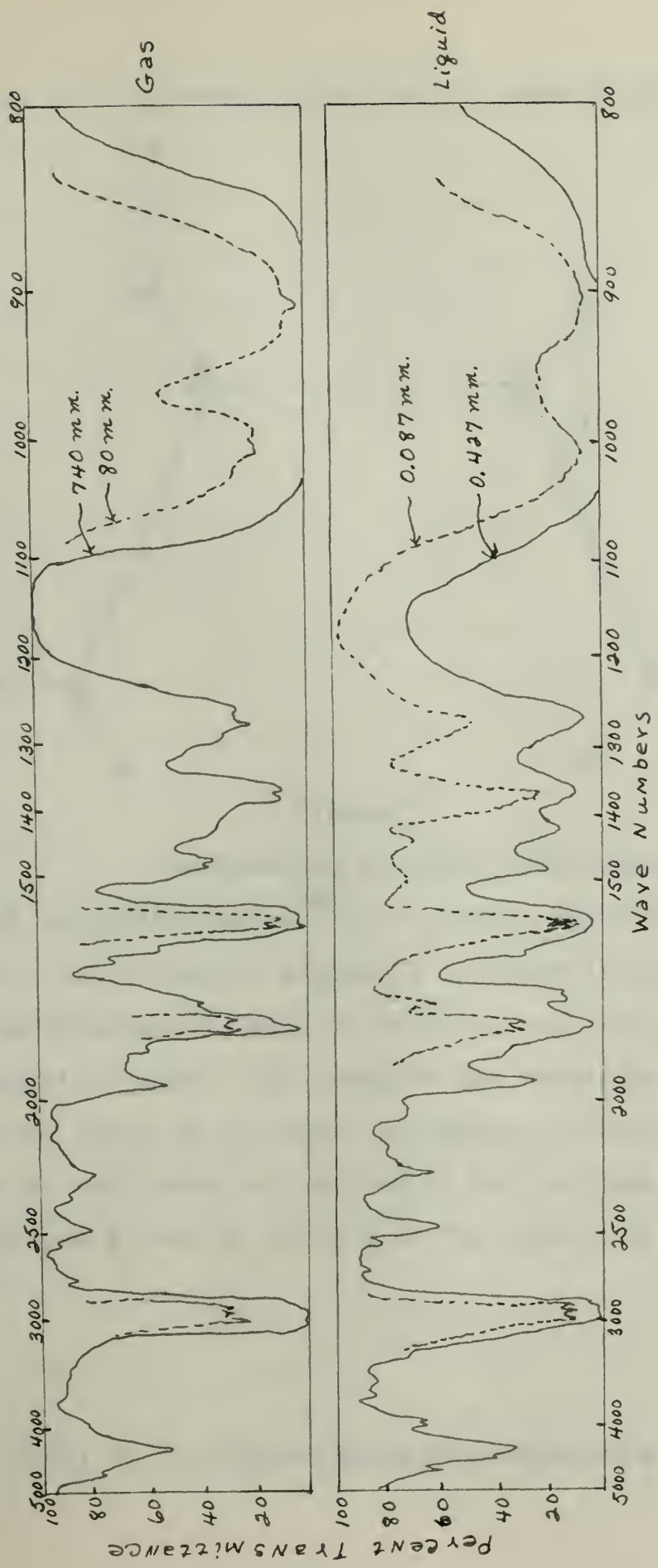


Figure 2.



The form of this normal vibration is shown in Fig. 3.

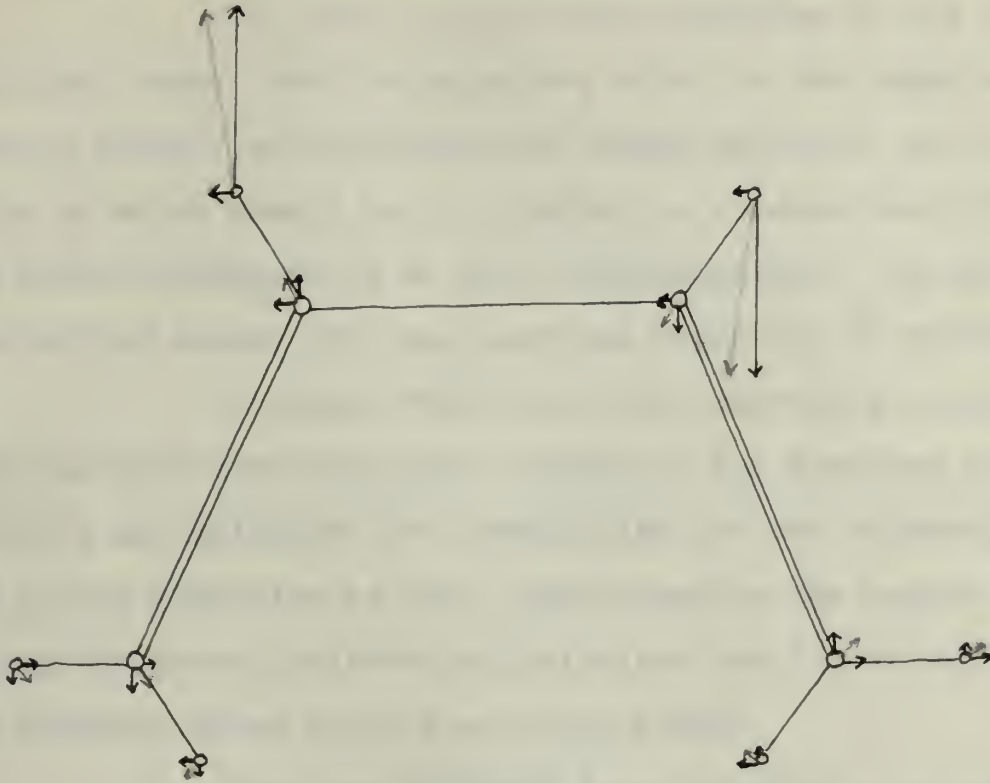


Figure 3.

The solution of these determinants was accomplished by Crout's method<sup>44</sup> for solving determinants. This method is also readily adaptable to computing machines and has the advantage as well of having a continual check on the numerical work. The forms of the remaining normal coordinates could be obtained, if desired, by determining the ratios of the minors of any row of both of the determinants for species  $A_1$  and  $B_1$  for all of the remaining values of  $\lambda$ .

44. Crout, P. D., Transactions Am. Inst. Elec. Eng. LX (1941)



### 5. An Approximate Calculation

In order to avoid the expansion of the eighth and ninth order secular equations prior to the adoption of Bryan's method, an approximation scheme was used, the results of which should be of interest in a comparison with the results obtained by an exact determination. The approximation scheme that was used was suggested by Herzberg<sup>45</sup>.

Consider first the force constants associated with the bond stretching and bending of the hydrogen atoms infinite and calculate the frequencies for the carbon-hydrogen groups vibrating as one. Then consider the masses of the carbon atoms infinite and calculate the vibrations of the hydrogen atoms about the carbon atoms.

When the hydrogen force constants are considered infinite, the only symmetry coordinates that remain in the potential energy expression are  $\Delta r_{12}$ ,  $\Delta r_{23}$ ,  $\Delta r_{34}$ ,  $\Delta \theta_1$ , and  $\Delta \theta_2$ . The only cartesian coordinates that need be considered then are  $z_1$ ,  $z_2$ ,  $z_3$ ,  $z_4$ ,  $y_1$ ,  $y_2$ ,  $y_3$  and  $y_4$ . For species  $A_1$  these are related by the symmetry treatment as follows:

$$z_4 = z_1, z_3 = z_2 = -\frac{M+2m}{M+m} z_1, y_4 = -y_1, y_3 = -y_2. \quad (1)$$

This then requires the solution of only a third order determinant.

Under these conditions the terms in the potential energy expression are

45. Herzberg, Op. Cit., p. 195



$$|\Delta r_{12}|^2 = \sqrt{\{(y_2 - y_1 + a)^2 + (-\mu z_1 + b)^2\} - |r_{12}^o|}^2 \quad (2)$$

$$|\Delta r_{23}|^2 = \{-2y_2 + c - |r_{23}^o|\}^2 \quad (3)$$

$$|\Delta r_{34}|^2 = \sqrt{\{(-y_1 + y_2 + a)^2 + (\mu z_1 - b)^2\} - |r_{34}^o|}^2 \quad (4)$$

$$|\Delta \theta_1|^2 = \frac{1}{\sin^2 \theta_1^o} \left\{ -\frac{[(y_2 - y_1 + a)(-2y_2 + c)]}{\sqrt{[(y_2 - y_1 + a)^2 + (-\mu z_1 + b)^2]} \sqrt{(-2y_2 + c)^2}} - \cos \theta_1^o \right\}^2 \quad (5)$$

$$|\Delta \theta_2|^2 = \frac{1}{\sin^2 \theta_2^o} \left\{ -\frac{(-2y_2 + c)(-y_1 + y_2 + a)}{\sqrt{(-2y_2 + c)^2} \sqrt{(-y_1 + y_2 + a)^2 + (\mu z_1 - b)^2}} - \cos \theta_2^o \right\}^2 \quad (6)$$

where

$$\mu = 1 - \frac{M - 2M}{M - M}$$

The expansion of the secular equation gives a third order equation in  $\lambda$  which is then solved by Horner's method to give the three roots. The three roots for this equation give three normal frequencies of vibration which, expressed in wave numbers, are

$$\frac{1}{\lambda_1} = 289 \text{cm}^{-1}, \quad \frac{1}{\lambda_2} = 1140 \text{cm}^{-1}, \quad \frac{1}{\lambda_3} = 1450 \text{cm}^{-1}. \quad (7)$$

Now to obtain the frequencies associated with the hydrogen motion the carbon masses are considered infinite which means that all coordinates associated with motion of the carbon atoms disappear.

The only remaining coordinates from the symmetry conditions are then

$$z_\alpha = z_\delta, \quad z_\sigma = z_\beta, \quad y_\alpha = -y_\delta, \quad y_\sigma = -y_\beta.$$



$$y_{\delta} = -y_{\gamma}, z_{\delta} = z_{\gamma} = -(z_{\alpha} + z_{\beta}). \quad (8)$$

This leaves five coordinates and requires the solution of a fifth order secular equation. The five roots of the secular equation again give five normal frequencies of vibration which are

$$\begin{aligned} \frac{1}{\lambda_1} &= 882\text{cm}^{-1}, \quad \frac{1}{\lambda_2} = 1350\text{cm}^{-1}, \quad \frac{1}{\lambda_3} = 2840\text{cm}^{-1} \\ \frac{1}{\lambda_4} &= 2920\text{cm}^{-1}, \quad \frac{1}{\lambda_5} = 3630\text{cm}^{-1}. \end{aligned} \quad (9)$$

For species  $B_1$  when the hydrogen bond constants are considered infinite, the coordinates remaining from the symmetry treatment are:

$$y_2 = -\eta y_1 \text{ and } z_2 = R y_1 - H z_1$$

where

$$\eta = \frac{M+2m}{M+m}, \quad R = \frac{\lambda + \rho + \mu - \eta}{1+x}, \quad H = \frac{\xi + \zeta + \nu}{1+x}$$

and

$$\lambda = \frac{2(b+h)}{M+m}, \quad \rho = \frac{2(b+e+h)}{2g+c}, \quad \xi = \frac{2a+2f+c}{2g+c}, \quad \zeta = \frac{2a-2d+c}{2g+c},$$

$$\alpha = \frac{Mc}{m(2g+c)}, \quad \mu = \frac{2M(b+h)}{m(2g+c)}, \quad \nu = \frac{M(2a+c)}{m(2g+c)}. \quad (10)$$

The process of solving for the roots is the same as that outlined for species  $A_1$ . In this case the solution of a second order secular equation is required which gives the frequencies

$$\frac{1}{\lambda_1} = 1600\text{cm}^{-1} \quad \text{and} \quad \frac{1}{\lambda_2} = 678\text{cm}^{-1}. \quad (11)$$

In species  $B_1$  when considering the frequencies due to the motion of the hydrogen atoms the same terms disappear in the potential function and the kinetic energy function as for  $A_1$  but the relations between the remaining

THE THEORY OF THE INTEGRAL

The theory of the integral is a branch of mathematics that deals with the study of functions and their properties. It is a fundamental part of calculus and is used in many areas of science and engineering.

$$\int_a^b f(x) dx = F(b) - F(a)$$

$$\int_a^b f(x) dx = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(x_k) \Delta x$$

The integral of a function f(x) over the interval [a, b] is denoted by  $\int_a^b f(x) dx$ . It represents the area under the curve of the function between the points a and b on the x-axis.

$$\int_a^b f(x) dx = \int_a^b g(x) dx + \int_a^b h(x) dx$$

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx$$

$$\int_a^b f(x) dx = \int_a^b f(x) dx + \int_a^b g(x) dx$$

$$\int_a^b f(x) dx = \int_a^b f(x) dx + \int_a^b g(x) dx$$

The integral of a function f(x) over the interval [a, b] is denoted by  $\int_a^b f(x) dx$ . It represents the area under the curve of the function between the points a and b on the x-axis.

$$\int_a^b f(x) dx = \int_a^b f(x) dx + \int_a^b g(x) dx$$

The integral of a function f(x) over the interval [a, b] is denoted by  $\int_a^b f(x) dx$ . It represents the area under the curve of the function between the points a and b on the x-axis.

cartesian coordinates are as follows:

$$z_\gamma = -z_\alpha, z_\sigma = -z_\beta, y_\eta = y_\alpha, y_\rho = y_\beta, \\ y_\delta = y_\gamma = -(y_\alpha + y_\beta) \text{ and } -z_\delta = z_\gamma = \lambda y_\beta + \rho y_\alpha - \xi z_\beta - \zeta z_\alpha. \quad (12)$$

This then requires the solution of a fourth order secular equation which gives the frequencies

$$\frac{1}{\lambda_1} = 1620\text{cm}^{-1}, \frac{1}{\lambda_2} = 2050\text{cm}^{-1}, \frac{1}{\lambda_3} = 2770\text{cm}^{-1}, \frac{1}{\lambda_4} = 2830\text{cm}^{-1}. \quad (13)$$

First of all, it is noticed in Table IV that in the process of making the approximation three roots disappear. The remaining roots, while having a similar overall pattern to those determined by the exact solution, differ from them by about 200 wave numbers in the case of the carbon oscillations and by a greater amount in the case of the hydrogen oscillations. The wave numbers in the approximation method are smaller in general than in the exact determination as would be expected from the general theory of oscillations.

TABLE IV.  
Comparison of Frequencies, in Wave Numbers  
From Approximate and Exact Calculations

$A_{1*}$	$A_{1c}$	$A_{1h}$	$B_{1*}$	$B_{1c}$	$B_{1h}$
434	289	...	894	678	...
1180	...	882	1230	...	...
1320	1140	...	1400	...	...
1640	1450	...	1730	1600	...
1640	...	1350	2430	...	1620
2060	...	...	2960	...	2050
2860	...	2840	3020	...	2770
2990	...	2920	4930	...	2830
2990	...	3630			

(\* indicates exact calculations, the subscript c indicates carbon vibrations, and h indicates hydrogen vibrations)



## 6. Calculation of Heat Capacity

From a knowledge of the fundamental frequencies of a molecule it is possible to calculate its thermodynamic quantities. It is generally best to calculate the partition function first since all of the other thermodynamic quantities can be determined from it. The partition function is given by<sup>46</sup>

$$Q = \sum g_n e^{-\frac{\epsilon_n}{kT}} \quad (1)$$

where  $\epsilon_n$  is the total energy of the atoms or molecules in a given equilibrium distribution,  $k$  is Boltzmann's constant,  $T$  is the absolute temperature and  $g_n$  is the statistical weight or degeneracy. This can be separated into a translational part and an internal part. The internal partition function, which is the part of interest here, is given by

$$Q_{int} = \sum g_{int} e^{-\frac{\epsilon_{int}}{kT}} \quad (2)$$

This part, again, is composed of contributions from electronic, vibrational and rotational energy, but in most cases the electronic contribution is negligible. Thus, there are only two parts remaining, the vibrational and rotational energy contributions. The partition function can then be written

$$Q_{int} = \sum_v (g_v e^{-G_0(v_1, v_2, \dots)} \frac{hc}{kT}) \sum g_r e^{-F_r(J, \dots) \frac{hc}{kT}} \quad (3)$$

where

$$\epsilon_{int} = [G_0(v_1, v_2, \dots) + F_r(J, \dots)] hc$$

46. Herzberg, Op. Cit., p. 501 ff.

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and  $F(J)$  is the rotational term value,  $J$  is the rotational quantum number,  $G_0$  is the vibrational term value, and  $v_i$  are the vibrational quantum numbers. If the interaction between vibration and rotation is neglected, this can be written as the product of the vibrational and rotational partition functions, and each part can be separately evaluated. Then

$$Q_v = \sum_v g_v e^{-G_0(v_1, v_2, \dots) \frac{hc}{kT}}, \quad Q_r = \sum_r g_r e^{-F_r(J, \dots) \frac{hc}{kT}} \quad (4)$$

Now, in the usual harmonic oscillator approximation we have

$$G_0(v_1, v_2, \dots) = \sum \omega_i v_i \quad (5)$$

where  $\omega_i$  are the frequencies in  $\text{cm}^{-1}$  for infinitesimal amplitudes. Then

$$Q_v = \left( \sum_{v_1} e^{-\omega_1 v_1 \frac{hc}{kT}} \right) \left( \sum_{v_2} e^{-\omega_2 v_2 \frac{hc}{kT}} \right) \dots \quad (6)$$

which can be written

$$Q_v = \left( 1 - e^{-\omega_1 \frac{hc}{kT}} \right)^{-1} \left( 1 - e^{-\omega_2 \frac{hc}{kT}} \right)^{-1} \dots \quad (7)$$

by making use of the relation

$$\sum_{v_i} e^{-\omega_i v_i \frac{hc}{kT}} = \frac{1}{1 - e^{-\omega_i \frac{hc}{kT}}}$$

If degeneracy exists and  $d_1, d_2, d_3, \dots$  represent the degrees of degeneracy of  $\omega_1, \omega_2, \omega_3, \dots$ , the partition function can be written

$$Q_v = \left( 1 - e^{-\omega_1 \frac{hc}{kT}} \right)^{-d_1} \left( 1 - e^{-\omega_2 \frac{hc}{kT}} \right)^{-d_2} \dots \quad (8)$$

In actual calculations the wave numbers  $\nu_i$  are used instead of the  $\omega_i$ .

For the rotational partition function the expression varies depending upon whether the molecule is linear, symmetric top or asymmetric top. For a linear molecule<sup>47</sup>

47. Herzberg, Op. Cit., p 505.



$$Q_r = \frac{kT}{hcB} + \frac{1}{3} + \frac{1}{15} \frac{hcB}{kT} + \frac{4}{315} \left(\frac{hcB}{kT}\right)^2 + \frac{1}{315} \left(\frac{hcB}{kT}\right)^3 + \dots, \quad (9)$$

for a rigid symmetric top molecule

$$Q_r = e^{\frac{Bhc}{4kT}} \sqrt{\frac{\pi}{B^2 A} \left(\frac{kT}{hc}\right)^3} \left[ 1 + \frac{1}{12} \left(1 - \frac{B}{A}\right) \frac{Bhc}{kT} + \frac{7}{480} \left(1 - \frac{B}{A}\right)^2 \left(\frac{Bhc}{kT}\right)^2 + \dots \right] \quad (10)$$

and for asymmetric top molecules

$$Q_r = e^{\sqrt{BC} \frac{hc}{4kT}} \sqrt{\frac{\pi}{ABC} \left(\frac{kT}{hc}\right)} \left[ 1 + \frac{1}{12} \left(1 - \frac{\sqrt{BC}}{A}\right) \frac{\sqrt{BC} hc}{kT} + \dots \right] \quad (11)$$

where A, B and C are the rotational constants.

Other thermodynamic quantities can then be calculated in terms of the partition function. For example, the specific heat at constant pressure is given by

$$C_{p, \text{int}}^{\circ} = R \frac{d}{dT} \left[ T^2 \frac{d(\ln Q_{\text{int}})}{dT} \right]. \quad (12)$$

Again, if the interaction of rotation and vibration is neglected, then

$$C_{p, r}^{\circ} = R \frac{d}{dT} \left[ T^2 \frac{d(\ln Q_r)}{dT} \right] \quad (13)$$

and

$$C_{p, v}^{\circ} = R \frac{d}{dT} \left[ T^2 \frac{d(\ln Q_v)}{dT} \right]. \quad (14)$$

For almost all gases the rotational contribution is practically equivalent to the classical values for ordinary temperatures. By substituting the value for  $Q_v$  in the above equation the value for the specific heat is

$$C_{p, v}^{\circ} = R \left(\frac{hc}{kT}\right)^2 \sum_i \frac{d_i w_i^2 e^{-\frac{w_i hc}{kT}}}{\left(1 - e^{-\frac{w_i hc}{kT}}\right)^2}. \quad (15)$$

The calculations for the value of the vibrational contributions to the heat capacity are simplified by the



use of a table published by Wilson<sup>48</sup> where the vibrational contributions to the heat capacity are given as a function of  $\frac{\omega}{T}$ . The calculated value for Butadiene determined for a temperature of 25°C with the aid of this table is

$$7.26 \text{ cal/mol deg.}$$

By adding this to the translational and rotational contributions as given by Wilson the heat capacity turns out to be

$$15.21 \text{ cal/mol deg.}$$

The best experimental value available obtained by comparison of the results published by Astor, Moissan, Gustave, Hardy, and Szasz<sup>49</sup> and Scott and Mellors<sup>50</sup> is

$$19.16 \text{ cal/mol deg.}$$

The difference between the observed value and the calculated value is due to internal rotation and could aid in establishing the height of the potential barrier in the molecule.

## 7. Evaluation of Results

The results obtained in this calculation indicate again the fact that it is possible to transfer force constants from parts of one molecule to another where similar structure exists. The fairly reasonable check of the pattern of the observed spectra with the calculated lines demonstrates that the force constants as chosen in the potential function probably agree favorably with the correct

48. Wilson, E. B. Jr., Chem. Rev. 27, 17 (1940)

49. Astor, John G. Moissan, Gustave W., Hardy, Howard C., and Szasz, George J., J. Chem. Phys. 12, 458 (1944)

50. Scott, Russell B. and Mellors, Jane W., J. Res. Nat. Bu. Stand. 34, 243 (1945)



values. The characteristic frequencies of various groups within molecules and of the motion within these groups as given by Herzberg<sup>51</sup> check fairly well with calculated frequencies which serves as an aid in identifying certain motions in the molecule. Exact agreement between observed and calculated lines is, of course, not possible because the valence force model is an approximation, and there may also be complications due to impurities in the experimental samples and because of the presence of combination and overtone bands.

Probably of greater significance in this work is the method used for expanding the secular equation. This part of the problem has always been the most tedious and laborious of all the work involved. By the use of this method, not only is it unnecessary to make use of approximations, but the exact expansion can in general be accomplished in less time and with less effort than previous approximation schemes required. Furthermore, a continuous check is provided on the numerical work thereby reducing the chance of error. Since the method is also readily adaptable to I.B.M. calculation, an additional saving in time and labor can be accomplished without the use of iteration or approximation schemes with their attendant loss or shift of frequencies.

51. Herzberg, Op. Cit., p. 195



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A B S T R A C T

The study of infra-red and Raman spectra and their relationship to the vibrations and rotations of atoms in molecules has become more and more a matter of interest to the physicist and chemist within the past several decades. The study of the vibrations of the atoms which give rise to the broad band spectra in the near infra-red has led to a more thorough understanding of the forces in the molecules including a theoretical explanation of valence. The study of the rotation of groups of atoms within a molecule as well as the rotation of molecules as a whole which give rise to the band spectra in the far infra-red and to fine structure in the near infra-red has led to a rather accurate means for determining the structure of molecules.

This paper deals with the theoretical determination of the vibrational frequencies of 1, 3- butadiene. As is well known, the frequencies obtained from a quantum mechanical treatment of the problem are the same as those resulting from a classical determination; consequently, though the quantum mechanical methods are outlined, the actual calculations are carried out by the classical method of treating small oscillations. The normal frequencies of vibration determined for an oscillating system having particles of masses equal to those of the masses of the atoms with force constants of magnitude equal to the forces actually existing in a molecule will be the same as the infra-red and Raman frequencies



emitted or absorbed by the molecule.

In general the force constants are unknown so that the problem essentially has to be worked backward by carrying it out algebraically and then, by making use of observed spectra, determining the force constants. For a large molecule, such as butadiene, this is not easy nor even feasible. Consequently, force constants determined by others for smaller molecules where the structure of part of the molecule is similar to a part of butadiene are used for a determination of the normal frequencies. The force constants in this work were transferred from the work on propylene by Wilson and Wells<sup>1</sup> and from a paper on force constants in organic molecules by Crawford and Brinkley<sup>2</sup>.

The cis-form was selected as the normal configuration for butadiene. The force field chosen was the valence type field. This means that the changes in bond length and changes in the bond angles from the equilibrium configuration were chosen as the coordinates for the potential function. The application of group theory to the symmetry in the molecule factored the secular equation obtained from the coefficients of the variables in the kinetic and potential energy expressions from a determinant of order twenty four to four determinants of order nine, eight, four and three. Since the

1. Wilson, E.B. Jr., and Wells, A.J., J. Chem. Phy. 9, 314 (1941)
2. Crawford, B.L.Jr., and Brinkley, S.R. Jr., J. Chem. Phy. 9, 69 (1941)



latter two contained only out-of-plane vibrations and would thus give zero frequencies with the type of force field chosen, only the two equations of order nine and eight had to be solved. These are, however, in determinantal form, and the process of expanding secular equations of this size is, in general, very laborious and tedious.

In order to reduce the amount of labor involved, an approximation scheme was attempted. As a first approximation, the carbon-hydrogen bond force constants, both stretching and bending, were considered infinite. This served then to increase the mass of the carbon atoms slightly while eliminating the hydrogen frequencies. Two secular equations of order three and two had to be expanded, which yielded an approximate value for the carbon skeletal vibrational frequencies. Secondly, the carbon masses were considered infinite and then the motions of the hydrogen atoms with respect to the carbon atoms were determined. This required the expansion of two secular equations of order five and four.

In the process of making these approximations, three frequencies disappeared, which should have or would have been determined by an exact expansion of the original secular equations. A method was then used for an exact expansion of the secular equations which was due to J. G. Bryan<sup>3</sup> and was developed for expanding matrix characteristic

3. Bryan, J.G., A Method for the Exact Determination of the Characteristic Equation and Latent Vectors of a Matrix with Applications to the Discriminant Function for More than Two Groups, Harvard Graduate School of Education Dissertation (1950)



equations and determining the latent vectors or characteristic vectors of a characteristic equation. The characteristic equation of a matrix is defined by

$$|A - \lambda I| = 0$$

where A is the original matrix and I is the unit matrix. While the secular equation is not, in general, in the form defined above, it can be put into this form by adding and subtracting rows and columns or multiples of rows and columns until the variable terms appear only on the diagonal and then dividing each column by the coefficient of the variable in that column. Since the secular equation will then be in the form as defined above, it is possible to make use of Bryan's method for an exact expansion of the characteristic equation. The method is described completely and the expansion of the eighth order secular equation is carried out in detail as an illustration of the method. The actual expansion of the secular equations by this process requires less time and effort, in general, than the approximation scheme. This method has an additional advantage in that a continual check is provided on the numerical work as the expansion proceeds. Furthermore, the method is readily adaptable to I.B.M. automatic punch card computers which can result in an additional saving in time and effort while at the same time carrying out an exact expansion rather than an approximation with its attendant loss or shift of frequencies.

After the equations were expanded, they were solved by



Horner's method yielding the seventeen required roots. These roots were proportional to the normal frequencies of vibration of the molecule and after solving for the frequencies in terms of wave numbers, they were compared with observed frequencies. The comparison showed a fairly good agreement between the observed and calculated frequencies. A comparison was also made between the frequencies obtained by the exact expansion and the approximation. This showed that the carbon vibrations in the approximation were all fairly uniformly displaced by about two hundred wave numbers toward lower frequencies as is to be expected from the general theory of small oscillations. The hydrogen frequencies were displaced by an even larger amount as also was to be expected but not in as regular a manner as the carbon oscillations.

The results of this paper again indicate that it is possible to transfer force constants from parts of one molecule to another where they exist in similar surroundings. The fairly good correlation between the observed and calculated frequencies indicates that the force constants as chosen are very nearly the correct values.

Probably of more significance in this paper is the application of Bryan's method to the exact expansion of the secular equation. This eliminates the necessity of introducing approximations, and the expansion can be carried out with less work and more of a check on the work than previously. This expansion as well as the solution of the expanded equation can be carried out on I.B.M. computers. Furthermore, the deter-



mination of the normal modes, which requires the solution of the ratios of the minors of any row of the secular equation with a given value for the frequency substituted, was performed by Crout's<sup>4</sup> method for the solution of determinants which is also readily adaptable to I.B.M. computers.

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